

Orbital angular momentum

①

$$\vec{L} = \vec{r} \times \vec{p}$$

$$(\vec{L})_k = \epsilon_{kij} x_i p_j$$

$$\text{In QM } [x_i, p_j] = i\hbar \delta_{ij}$$

$$\begin{aligned} (a) \quad [x_i, L_j] &= [x_i, \epsilon_{jab} x_a p_b] = \epsilon_{jab} [x_i, x_a p_b] \\ &= \epsilon_{jab} [x_i x_a p_b - \cancel{x_a p_b x_i} - x_a p_b x_i] \\ &= \epsilon_{jab} (x_a [x_i, p_b]) = i\hbar \epsilon_{jab} x_a \delta_{ib} = i\hbar \epsilon_{aji} x_a \end{aligned}$$

$$\begin{aligned} (b) \text{ and } [p_i, L_j] &= \cancel{\epsilon_{jab} x_a p_b} [p_i, \epsilon_{jab} x_a p_b] \\ &= \epsilon_{jab} (p_i x_a p_b - x_a p_b p_i) = \epsilon_{jab} [p_i, x_a] p_b \\ &= -i\hbar \delta_{ia} \epsilon_{jab} p_b = i\hbar \epsilon_{baj} p_b \end{aligned}$$

$$\begin{aligned} (c) \quad [L_i, L_j] &= [\epsilon_{iab} x_a p_b, L_j] = \epsilon_{iab} [x_a p_b, L_j] \\ &= \epsilon_{iab} (x_a p_b L_j - \cancel{x_a L_j p_b} + \cancel{x_a L_j p_b} - p_b L_j x_a) \\ &= [\epsilon_{iab} x_a p_b, \epsilon_{jcd} x_c p_d] = \epsilon_{iab} \epsilon_{jcd} [x_a p_b, x_c p_d] \\ &= \epsilon_{iab} \epsilon_{jcd} (x_a p_b x_c p_d - x_c p_d x_a p_b) \\ &= \epsilon_{iab} \epsilon_{jcd} (x_a (\cancel{x_c p_b} - i\hbar \delta_{bc}) p_d - x_c (\cancel{x_a p_d} - i\hbar \delta_{ad}) p_b) \\ &= i\hbar \epsilon_{iab} \epsilon_{jcd} (-\delta_{bc} x_a p_d + \delta_{ad} x_c p_b) \\ &= i\hbar (-\epsilon_{iab} \epsilon_{jbd} x_a p_d + \epsilon_{iab} \epsilon_{jca} x_c p_b) \\ &= i\hbar (-(\delta_{di} \delta_{ja} - \delta_{da} \delta_{ji}) x_a p_d + (\delta_{bj} \delta_{ic} - \delta_{bc} \delta_{ij}) x_c p_b) \\ &= i\hbar (x_i p_j - x_j p_i) = i\hbar \epsilon_{ijk} (\epsilon_{kab} x_a p_b) \end{aligned}$$

$$\Rightarrow [L_i, L_j] = i\hbar \epsilon_{ijk} L_k$$

★ Therefore, from the general discussion of QM angular momentum, it follows that

$$L^2 |l, m\rangle = \hbar^2 l(l+1) |l, m\rangle$$

$$L_z |l, m\rangle = \hbar m |l, m\rangle$$

$$L_{\pm} |l, m\rangle = \sqrt{l(l+1) - m(m \pm 1)} |l, m \pm 1\rangle$$

However, there is an important restriction: ℓ can only be integer!!

To see this, let

$$a = \frac{x + i p_x}{\sqrt{2}}, \quad a^\dagger = \frac{x - i p_x}{\sqrt{2}}, \quad \text{then } [a, a^\dagger] = 1$$

$$b = \frac{y + i p_y}{\sqrt{2}}, \quad b^\dagger = \frac{y - i p_y}{\sqrt{2}}, \quad [b, b^\dagger] = 1$$

and $[a, b^\dagger] = [a, b] = 0$

also, L_z can be expressed as

$$\begin{aligned} i L_z &= a^\dagger b - b^\dagger a = \frac{1}{\sqrt{2}} (x - i p_x) \frac{1}{\sqrt{2}} (y + i p_y) - \frac{1}{\sqrt{2}} (y - i p_y) \frac{1}{\sqrt{2}} (x + i p_x) \\ &= -\frac{i}{2} p_x y + \frac{i}{2} x p_y + \frac{i}{2} x p_y - \frac{i}{2} y p_x \end{aligned}$$

define $d = \frac{a - i b}{\sqrt{2}}, \quad c = \frac{a + i b}{\sqrt{2}} \Rightarrow a = \frac{1}{\sqrt{2}} (c + d), \quad b = \frac{i}{\sqrt{2}} (c - d)$

thus $[c, c^\dagger] = \frac{1}{2} [a + i b, a^\dagger - i b^\dagger] = 1$

$$[d, d^\dagger] = 1$$

$$[c, d] = \frac{1}{2} [a + i b, a - i b] = 0 = \frac{1}{2} [a + i b, a^\dagger + i b^\dagger] = [c, d^\dagger]$$

So, L_z can be written as

$$L_z = -i(a^\dagger b - b^\dagger a) = d^\dagger d - c^\dagger c$$

from our study of SHO, we know that $d^\dagger d$ & $c^\dagger c$ have ~~zero~~ zero or positive integer eigenvalues. $\Rightarrow m$ must be integer. ($\hbar$)
(in the unit of $\hbar$) $\Rightarrow \ell$ must also be integer ($\hbar$)

Usually, people use spherical polar coordinates.

$$x = r \sin \theta \cos \phi, \quad y = r \sin \theta \sin \phi, \quad z = r \cos \theta$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \phi}{\partial x} \frac{\partial}{\partial \phi} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta}$$

$$\tan \phi = \frac{y}{x}$$

$$= \frac{x}{r} \frac{\partial}{\partial x} - \frac{y}{r^2} c\phi \frac{\partial}{\partial \phi} + \frac{z}{r \sin \theta} \frac{\partial}{\partial \theta}$$

$$\theta = \cos^{-1} \frac{z}{\sqrt{x^2 + y^2 + z^2}}$$

$$= \sin \theta \cos \phi \frac{\partial}{\partial r} + \frac{\sin \phi}{r \sin \theta} \frac{\partial}{\partial \phi} + \frac{\cos \phi \cos \theta}{r} \frac{\partial}{\partial \theta}$$

$$\frac{\partial \phi}{\partial x} = -\frac{y}{x^2}$$

$$\frac{d}{dy} = \frac{\partial r}{\partial y} \frac{\partial}{\partial r} + \frac{\partial \phi}{\partial y} \frac{\partial}{\partial \phi} + \frac{\partial \theta}{\partial y} \frac{\partial}{\partial \theta}$$

$$= \frac{y}{r} \frac{\partial}{\partial r} + \frac{\cos \phi}{x} \frac{\partial}{\partial \phi} + \frac{yz}{r^3 \sin \theta} \frac{\partial}{\partial \theta} = \sin \theta \sin \phi \frac{\partial}{\partial r} + \frac{\cos \phi}{r \sin \theta} \frac{\partial}{\partial \phi} + \frac{\sin \phi \cos \theta}{r} \frac{\partial}{\partial \theta}$$

$$L_z = x p_y - y p_x = -i\hbar \left(x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right)$$

$$= -i\hbar \left(r \sin \theta \cos \phi \left(\sin \theta \sin \phi \frac{\partial}{\partial r} + \frac{\cos \phi}{r \sin \theta} \frac{\partial}{\partial \phi} + \frac{\sin \phi \cos \theta}{r} \frac{\partial}{\partial \theta} \right) - r \sin \theta \sin \phi \left(\sin \theta \cos \phi \frac{\partial}{\partial r} - \frac{\sin \phi}{r \sin \theta} \frac{\partial}{\partial \phi} + \frac{\cos \phi \cos \theta}{r} \frac{\partial}{\partial \theta} \right) \right)$$

$$\boxed{L_z = -i\hbar \frac{\partial}{\partial \phi}}$$

since $L_z |l, m\rangle = m\hbar |l, m\rangle$

$$\langle x | -i\hbar \frac{\partial}{\partial \phi} |l, m\rangle = m\hbar \langle x |l, m\rangle \Rightarrow \langle x |l, m\rangle = f_{lm}(\theta) e^{+im\phi}$$

$$\psi_{lm} = f_{lm}(\theta) e^{+im\phi}$$

Now since $L^2 = L_- L_+ + L_z (L_z + \hbar)$

and $L_{\pm} = L_x \pm iL_y$

$$= (y p_z - z p_y) \pm i(z p_x - x p_z)$$

$$= -i\hbar \left(y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right) \pm \hbar \left(z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z} \right)$$

$$= -i\hbar \left(r \sin \theta \cos \phi \left(\cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \right) - r \cos \theta \left(\sin \theta \sin \phi \frac{\partial}{\partial r} + \frac{\cos \phi}{r \sin \theta} \frac{\partial}{\partial \phi} + \frac{\sin \phi \cos \theta}{r} \frac{\partial}{\partial \theta} \right) \right. \\ \left. \pm \hbar \left(r \cos \theta \left(\sin \theta \cos \phi \frac{\partial}{\partial r} - \frac{\sin \phi}{r \sin \theta} \frac{\partial}{\partial \phi} + \frac{\cos \phi \cos \theta}{r} \frac{\partial}{\partial \theta} \right) - r \sin \theta \sin \phi \left(\cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \right) \right) \right)$$

$$\frac{\partial}{\partial z} = \frac{\partial r}{\partial z} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial z} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial z} \frac{\partial}{\partial \phi}$$

$$= \frac{z}{r} \frac{\partial}{\partial r} - \frac{1}{\sin \theta} \left(\frac{1}{r} - \frac{z^2}{r^3} \right) \frac{\partial}{\partial \theta}$$

$$= \cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta}$$

$$= \hbar \left(\mp x - i y \right) \frac{\partial}{\partial z} + \hbar z \left(i \frac{\partial}{\partial y} \pm \frac{\partial}{\partial x} \right)$$

$$= \mp \hbar e^{\pm i\phi} \sin \theta r \left(\cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \right) + \hbar r \cos \theta \left(i \left(\sin \theta \sin \phi \frac{\partial}{\partial r} + \frac{\cos \phi}{r \sin \theta} \frac{\partial}{\partial \phi} + \frac{\sin \phi \cos \theta}{r} \frac{\partial}{\partial \theta} \right) \pm \left(\sin \theta \cos \phi \frac{\partial}{\partial r} - \frac{\sin \phi}{r \sin \theta} \frac{\partial}{\partial \phi} + \frac{\cos \phi \cos \theta}{r} \frac{\partial}{\partial \theta} \right) \right)$$

$$= \mp \hbar e^{\pm i\phi} \sin \theta r \left(\cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \right) + \hbar r \cos \theta \left(\pm \sin \theta e^{\pm i\phi} \frac{\partial}{\partial r} + i \frac{e^{\pm i\phi}}{r \sin \theta} \frac{\partial}{\partial \phi} \pm \frac{\cos \theta}{r} e^{\pm i\phi} \frac{\partial}{\partial \theta} \right)$$

$$\boxed{L_{\pm} = \hbar e^{\pm i\phi} \left(\pm \frac{\partial}{\partial \theta} + i \frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \phi} \right)}$$

Thus, $L^2 = \hbar^2 e^{-i\phi} \left(-\frac{\partial}{\partial \theta} + i \frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \phi} \right) \left(e^{+i\phi} \left(\frac{\partial}{\partial \theta} + i \frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \phi} \right) \right) - i\hbar \frac{\partial}{\partial \phi} \left(-i\hbar \frac{\partial}{\partial \phi} + 1 \right)$

$$= -\hbar^2 \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right]$$

$$\Rightarrow L^2 \psi_{lm} = -\hbar^2 \left[\frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial}{\partial\theta} \right) + \frac{1}{\sin^2\theta} \frac{\partial^2}{\partial\phi^2} \right] \psi_{lm} = \hbar^2 l(l+1) \psi_{lm}$$

$$\psi_{lm} = f_{lm}(\theta) e^{+im\phi}$$

$$\Rightarrow \left(\frac{\partial^2}{\partial\theta^2} + \frac{\cos\theta}{\sin\theta} \frac{\partial}{\partial\theta} + l(l+1) - \frac{m^2}{\sin^2\theta} \right) f_{lm}(\theta) = 0$$

The solution that is analytic for all θ is the associated Legendre polynomial

$$P_l^m \Rightarrow \psi_{lm} = \underbrace{N_{lm}}_{\text{normalization}} \times P_l^m(\theta) \times \exp(im\phi)$$

with a standard choice of N_{lm} , we have the spherical harmonics.

$$\Rightarrow Y_l^m(\theta, \phi) = \sqrt{\frac{2l+1}{4\pi} \frac{(l-m)!}{(l+m)!}} \frac{1}{2^l l!} e^{im\phi} (-\sin\theta)^m \left(\frac{d}{d\cos\theta} \right)^{l+m} (\cos^2\theta - 1)^l$$

$$\text{defined for } m \geq 0, \text{ and } Y_l^{-m}(\theta, \phi) = (-1)^m Y_l^{m*}(\theta, \phi)$$

$$\int Y_{l'}^{m'*} Y_l^m d(\cos\theta) d(\phi) = \delta_{ll'} \delta_{mm'}$$

$$Y_0^0 = \frac{1}{\sqrt{4\pi}}, \quad Y_1^0 = -\sqrt{\frac{3}{8\pi}} \cos\theta, \quad Y_1^{\pm 1} = \pm \sqrt{\frac{3}{8\pi}} \sin\theta e^{\pm i\phi}$$

$$Y_2^0 = \sqrt{\frac{5}{4\pi}} \left(\frac{3}{2} \cos^2\theta - \frac{1}{2} \right)$$

$$Y_2^{\pm 1} = \mp \sqrt{\frac{15}{8\pi}} \sin\theta \cos\theta e^{\pm i\phi}, \quad Y_2^{\pm 2} = \sqrt{\frac{15}{32\pi}} \sin^2\theta e^{\pm 2i\phi}$$

$$Y_2^2 = \sqrt{\frac{15}{32\pi}} \sin^2\theta e^{+2i\phi}, \quad Y_2^{-2} = \sqrt{\frac{15}{32\pi}} \sin^2\theta e^{-2i\phi}$$

(5)

$$\langle \hat{n} | L_- | l, -l \rangle = 0$$

$$= \hbar e^{-i\phi} \left(-\frac{\partial}{\partial \theta} + i \frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \phi} \right) f_{l,-l}(\theta) e^{-il\phi} = 0$$

$$\Rightarrow -f'_{l,-l} + l \frac{\cos \theta}{\sin \theta} f_{l,-l} = 0$$

$$\frac{df'}{f} = l \frac{\cos \theta}{\sin \theta} d\theta$$

$$\Rightarrow d(\ln f) = l d(\ln \sin \theta) \Rightarrow f_{l,-l}(\theta) = N \sin^l \theta$$

$$\Rightarrow Y_{l,-l}(\theta, \phi) = N \sin^l \theta e^{-il\phi}$$

The normalization const is determined by requiring that

$$1 = \int d\phi \int d(\cos \theta) |N|^2 \sin^{2l} \theta = |N|^2 2\pi \int_{-1}^1 d(\cos \theta) (1 - \cos^2 \theta)^l = 2\pi |N|^2 \int_{-1}^1 dx (1 - x^2)^l$$

$$= 2\pi |N|^2 \int_{-1}^1 dx (1+x)^l (1-x)^l \quad \text{change variable } t = \frac{1+x}{2}, \quad dt = \frac{1}{2} dx$$

$$= 2\pi |N|^2 \int_0^1 2 dt (2t)^l (2(1-t))^l = 2\pi |N|^2 2^{(2l+1)} \int_0^1 dt t^l (1-t)^l$$

The last expression integral is Beta function

$$B(p, q) = \int_0^1 dt t^{p-1} (1-t)^{q-1} = \frac{\Gamma(p) \Gamma(q)}{\Gamma(p+q)} \quad \Gamma(p) = (p-1)!$$

$$\Rightarrow 1 = 2\pi |N|^2 2^{(2l+1)} \frac{\Gamma(l+1) \Gamma(l+1)}{\Gamma(2l+2)} = 2\pi |N|^2 2^{(2l+1)} \frac{(l!)^2}{(2l+1)!}$$

$$\text{or } |N| = \frac{1}{2^l l! \sqrt{\frac{(2l+1)!}{4\pi}}}, \text{ by convention, we choose } N \text{ to be real.}$$

$$\Rightarrow Y_{l,-l}(\theta, \phi) = \frac{1}{2^l l! \sqrt{\frac{(2l+1)!}{4\pi}}} \sin^l \theta e^{-il\phi}$$

$$\begin{aligned} \langle \hat{n} | L_+ | l, m \rangle &= \hbar \sqrt{l(l+1) - m(m+1)} |l, m+1\rangle \\ &= \hbar \sqrt{(l-m)(l+m+1)} |l, m+1\rangle \end{aligned}$$

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Then we find

$$\begin{aligned}
 Y_l^m(\theta, \phi) &= \frac{1}{\sqrt{(l-m+1)(l+m)}} e^{im\phi} \left(\frac{\partial}{\partial \theta} + i \frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \phi} \right) Y_l^{m-1}(\theta, \phi) \\
 &= \frac{1}{\sqrt{(l-m+1)(l+m)}} \frac{1}{\sqrt{(l+m-1)(l-m+2)}} \cdots \frac{1}{\sqrt{(1)(l+1)}} \left[e^{im\phi} \left(\frac{\partial}{\partial \theta} + i \frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \phi} \right) \right]^{l+m} Y_l^{-l}(\theta, \phi) \\
 &= \sqrt{\frac{(l-m)!}{(2l)!(l+m)!}} \left[e^{im\phi} \left(\frac{\partial}{\partial \theta} + i \frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \phi} \right) \right]^{l+m} Y_l^{-l}(\theta, \phi) \\
 &\quad \begin{array}{cc} \uparrow & \downarrow \\ \text{increase by} & \text{give eigenvalue } i m \\ +1 & \end{array} \\
 &= \frac{1}{2^l l!} \sqrt{\frac{(2l+1)!}{4\pi}} \sqrt{\frac{(l-m)!}{(2l)!(l+m)!}} e^{im\phi} \left(\frac{\partial}{\partial \theta} - (m-1) \frac{\cos \theta}{\sin \theta} \right) \left(\frac{\partial}{\partial \theta} - (m-2) \frac{\cos \theta}{\sin \theta} \right) \cdots \\
 &\quad \cdots \left(\frac{\partial}{\partial \theta} + (l-1) \frac{\cos \theta}{\sin \theta} \right) \left[\frac{\partial}{\partial \theta} + l \frac{\cos \theta}{\sin \theta} \right] \sin^l \theta
 \end{aligned}$$

Now applying the trick that

$$\left(\frac{\partial}{\partial \theta} + k \frac{\cos \theta}{\sin \theta} \right) = \frac{1}{\sin^k \theta} \frac{\partial}{\partial \theta} \sin^k \theta = k \frac{\sin^{k-1} \theta \cos \theta}{\sin^k \theta} + \frac{\partial}{\partial \theta}$$

$$\begin{aligned}
 \Rightarrow Y_l^m(\theta, \phi) &= \frac{1}{2^l l!} \sqrt{\frac{(2l+1)(l-m)!}{4\pi(l+m)!}} e^{im\phi} \left(\frac{1}{\sin^{l-m} \theta} \frac{\partial}{\partial \theta} \sin^{l-m} \theta \right) \cdots \\
 &\quad \cdots \left(\frac{1}{\sin^{l-1} \theta} \frac{\partial}{\partial \theta} \sin^{l-1} \theta \right) \left(\frac{1}{\sin^l \theta} \frac{\partial}{\partial \theta} \sin^l \theta \right) \sin^l \theta \\
 &= \frac{1}{2^l l!} \sqrt{\frac{(2l+1)(l-m)!}{4\pi(l+m)!}} e^{im\phi} \sin^m \theta \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \right)^{l+m} \sin^{2l} \theta
 \end{aligned}$$

$$Y_l^m(\theta, \phi) = \frac{(-1)^{l+m}}{2^l l!} \sqrt{\frac{(2l+1)(l-m)!}{4\pi(l+m)!}} e^{im\phi} (1-x^2)^{\frac{m}{2}} \left(\frac{\partial}{\partial x} \right)^{l+m} (1-x^2)^l$$

$$x = \cos \theta$$

$$dx = -\sin \theta d\theta$$

$$\frac{\partial}{\partial \theta} = \frac{\partial x}{\partial \theta} \frac{\partial}{\partial x}$$

works for $m > 0$

$$\text{and } Y_l^{-m}(\theta, \phi) = (-1)^m Y_l^m(\theta, \phi)^*$$