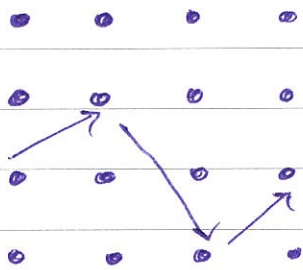


Waves in periodic structures

From classical point of view, it is very



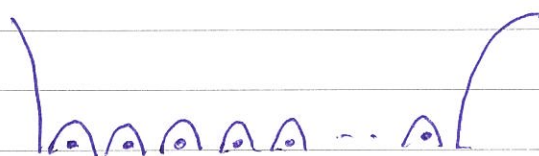
difficult to understand why the mean free path of electrons can be very large!

Bloch (1928) provided the solution to this puzzle in his thesis by pointing out that in the presence of periodic potential, $\frac{v_{ch}}{a}$ electron

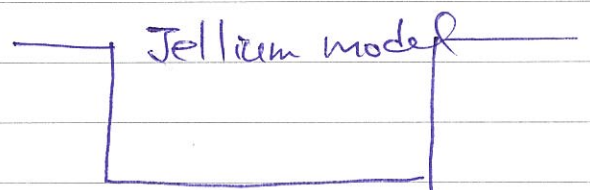
can maintain the coherence of its wave function as if it does not suffer any scattering from the lattice.

This is summarized in the Bloch theorem and the corresponding lattice effect is the most important correction to the Sommerfeld free electron theory.

The difference in treating ions in two theories can be summarized as:



\approx periodic potential



ion = smooth background (Sommerfeld theory)

What is found by Bloch is actually a general phenomenon for any waves in a periodic structure.

Generally, the wave function $\psi(\vec{r})$ satisfies

$$\hat{H}(\vec{r}) \psi(\vec{r}) = \lambda \psi(\vec{r})$$

with $\hat{H}(\vec{r} + \vec{R}) = \hat{H}(\vec{r})$, $\vec{R} = n_1 \vec{a}_1 + n_2 \vec{a}_2 + n_3 \vec{a}_3$

\vec{a}_i = primitive vectors of the crystal.

examples:

1. Electromagnetic waves in a photonic crystal

$$\nabla \times \vec{E} = -\frac{1}{c} \frac{d\vec{B}}{dt}, \quad \nabla \cdot \vec{D} = 4\pi\rho$$

$$\nabla \times \vec{H} = \frac{1}{c} \frac{d\vec{D}}{dt} + \frac{4\pi}{c} \vec{J} \quad (\vec{J}_{free} = 0)$$

$$\vec{D} = \epsilon \vec{E}, \quad \vec{B} = \mu \vec{H}$$

$$\therefore \nabla \times \left(\frac{1}{\epsilon} \vec{D} \right) = -\frac{1}{c} \frac{d}{dt} (\mu \vec{H}) \Rightarrow \frac{1}{\mu} \nabla \times \frac{\vec{D}}{\epsilon} = -\frac{1}{c} \frac{d\vec{H}}{dt}$$

take $\nabla \times$ & using $\nabla \times \vec{H} = \frac{1}{c} \frac{d\vec{D}}{dt} + \frac{4\pi}{c} \vec{J}$

$$\Rightarrow \frac{1}{c^2} \frac{d^2 \vec{D}}{dt^2} + \nabla \times \left(\frac{1}{\mu \epsilon} \nabla \times \frac{\vec{D}}{\epsilon} \right) = 0$$

$$\vec{D} = \vec{D}(\vec{r}) e^{i\omega t} \Rightarrow \nabla \times \left(\frac{1}{\mu \epsilon} \nabla \times \frac{1}{\epsilon} \vec{D} \right) = \lambda \vec{D}(\vec{r})$$

$$\lambda = \omega^2 / c^2 \quad \hat{H}$$

$$\therefore \text{if } \epsilon(\vec{r} + \vec{R}) = \epsilon(\vec{r}), \quad \mu(\vec{r} + \vec{R}) = \mu(\vec{r}), \quad \hat{H}(\vec{r} + \vec{R}) = \hat{H}(\vec{r})$$

2. Elastic waves in crystals

$$\hat{H} \rightarrow D(\vec{k}) \cdot \epsilon(k) = \lambda \epsilon(k)$$

$$\lambda = M\omega^2$$

$$D(\vec{k}) = \sum_{\vec{R}} D(\vec{R}) e^{-i\vec{k} \cdot \vec{R}}$$

$$D(\vec{k} + \vec{G}) = D(\vec{k}) \quad \text{periodic } k \text{ space}$$

Elastic wave in a medium

(phononic crystal, acoustic waves in a medium)

$$\rho(r) \frac{\partial^2 u_\alpha}{\partial t^2} = \frac{\partial}{\partial x_\alpha} \left(\lambda(r) \frac{\partial u_\beta}{\partial x_\beta} \right) + \frac{\partial}{\partial x_\beta} \left[\mu(r) \left(\frac{\partial u_\alpha}{\partial x_\beta} + \frac{\partial u_\beta}{\partial x_\alpha} \right) \right]$$

$$\lambda(\vec{r} + \vec{R}) = \lambda(\vec{r}), \quad \mu(\vec{r} + \vec{R}) = \mu(\vec{r}), \quad \rho(\vec{r} + \vec{R}) = \rho(\vec{r})$$

Lamé coefficient

$$u_\alpha = u_\alpha(\vec{r}) e^{i\omega t}$$

$$-\frac{1}{\rho(r)} \frac{\partial}{\partial x_\alpha} \left[\lambda(r) \frac{\partial u_\beta}{\partial x_\beta} \right] + \frac{\partial}{\partial x_\beta} \left[\mu(r) \left(\frac{\partial u_\alpha}{\partial x_\beta} + \frac{\partial u_\beta}{\partial x_\alpha} \right) \right] = \omega^2 u_\alpha$$

$$\hat{H}_{\alpha\beta} u_\beta$$

3. Schrödinger equation

$$\left[\frac{-\hbar^2}{2m} \nabla^2 + U(r) \right] \psi(\vec{r}) = E \psi(\vec{r})$$

$$\hat{H}(r)$$

$$U(\vec{r} + \vec{R}) = U(\vec{r})$$

Naively, one would think that since

$$A(\vec{r}+\vec{R}) = A(\vec{r}), \quad \psi(\vec{r}+\vec{R}) = \psi(\vec{r})$$

This is not correct as one can see

for the free Schrödinger equation, $U=0$

$$\psi(\vec{r}) = e^{i\vec{k}\cdot\vec{r}}, \quad \psi(\vec{r}+\vec{R}) = e^{i\vec{k}\cdot\vec{R}} e^{i\vec{k}\cdot\vec{r}} \\ \neq e^{i\vec{k}\cdot\vec{r}} = \psi(\vec{r})!$$

The probability density, $|\psi(\vec{r})|^2$, however,

$$\text{satisfies } |\psi(\vec{r}+\vec{R})|^2 = |\psi(\vec{r})|^2.$$

Bloch proves: there exists a \vec{k} such that

Bloch theorem: $\psi(\vec{r}+\vec{R}) = e^{i\vec{k}\cdot\vec{R}} \psi(\vec{r})$

so that we can label ψ by \vec{k}

$$\psi_{\vec{k}}(\vec{r}+\vec{R}) = e^{i\vec{k}\cdot\vec{R}} \psi_{\vec{k}}(\vec{r}) \quad (1)$$

alternative form: $\psi_{\vec{k}}(\vec{r}) = e^{i\vec{k}\cdot\vec{r}} u_{\vec{k}}(\vec{r}) \quad (2)$

$u_{\vec{k}}(\vec{r})$: Bloch function, & $u_{\vec{k}}(\vec{r}+\vec{R}) = u_{\vec{k}}(\vec{r})$

(2) implies (1): $\psi_{\vec{k}}(\vec{r}+\vec{R}) = e^{i\vec{k}\cdot\vec{R}} \left[e^{i\vec{k}\cdot\vec{r}} \underbrace{u_{\vec{k}}(\vec{r}+\vec{R})}_{u_{\vec{k}}(\vec{r})} \right]$

$$= e^{i\vec{k}\cdot\vec{R}} \psi_{\vec{k}}(\vec{r})$$

(1) implies (2): set $u_{\vec{k}}(\vec{r}) = e^{-i\vec{k}\cdot\vec{r}} \psi_{\vec{k}}(\vec{r})$

$$\psi_{\vec{k}}(\vec{r}) = e^{i\vec{k}\cdot\vec{r}} e^{-i\vec{k}\cdot\vec{r}} \psi_{\vec{k}}(\vec{r}) = e^{i\vec{k}\cdot\vec{r}} u_{\vec{k}}(\vec{r})$$

$$u_{\vec{k}}(\vec{r}+\vec{R}) = e^{-i\vec{k}\cdot\vec{R}} e^{-i\vec{k}\cdot\vec{r}} \psi_{\vec{k}}(\vec{r}+\vec{R}) = e^{-i\vec{k}\cdot\vec{r}} \psi_{\vec{k}}(\vec{r}) = u_{\vec{k}}(\vec{r})$$

To prove the Bloch theorem, we first construct

the translational operator \hat{T}_R

$$\begin{aligned}\hat{T}_R \psi(\vec{r}) &\equiv \psi(\vec{r} + \vec{R}) = \left[1 + \vec{R} \cdot \vec{\nabla} + \frac{1}{2!} (\vec{R} \cdot \vec{\nabla})^2 + \dots \right] \psi(\vec{r}) \\ &= e^{\vec{R} \cdot \vec{\nabla}} \psi(\vec{r})\end{aligned}$$

$$\therefore \hat{T}_R = e^{\frac{i}{\hbar} \vec{R} \cdot \vec{p}}$$

Now, from $\hat{H}(\vec{r}) \psi(\vec{r}) = \lambda \psi(\vec{r})$, we get

$$\begin{aligned}\hat{H}(\vec{r} + \vec{R}) \psi(\vec{r} + \vec{R}) &= \lambda \psi(\vec{r} + \vec{R}) \\ &= \lambda \hat{T}_R \psi(\vec{r})\end{aligned}$$

$$\therefore \hat{H}(\vec{r} + \vec{R}) \hat{T}_R \psi(\vec{r}) = \lambda \hat{T}_R \psi(\vec{r})$$

$$\hat{T}_R^{-1} \hat{H}(\vec{r} + \vec{R}) \hat{T}_R \psi(\vec{r}) = \lambda \psi(\vec{r})$$

$$\text{Hence } H(\vec{r}) = \hat{T}_R^{-1} \hat{H}(\vec{r} + \vec{R}) \hat{T}_R$$

that is, under translation, \hat{H} transforms as

$$\hat{H}(\vec{r} + \vec{R}) = \hat{T}_R H(\vec{r}) \hat{T}_R^{-1} \quad \text{--- (3)}$$

For periodic structures, $\hat{H}(\vec{r} + \vec{R}) = \hat{H}(\vec{r})$

$$\therefore \text{Eq. (3) implies } \hat{T}_R \hat{H}(\vec{r}) \hat{T}_R^{-1} = \hat{H}(\vec{r})$$

$$\therefore \hat{T}_R \hat{H}(\vec{r}) = \hat{H}(\vec{r}) \hat{T}_R$$

$$[\hat{T}_R, \hat{H}(\vec{r})] = 0 \quad \text{--- (4)}$$

Eq. (4) implies \hat{H} & $T_{\vec{R}}$ can be diagonalized

simultaneously. That is, one can find a set of eigenfunctions such that

$$T_{\vec{R}} \psi(\vec{r}) = C(\vec{R}) \psi(\vec{r})$$

$$\hat{H}(\vec{r}) \psi = \lambda \psi(\vec{r})$$

To find $C(\vec{R})$, we note that

$$T_{\vec{R}'} T_{\vec{R}} = T_{\vec{R}+\vec{R}'}$$

$$\therefore T_{\vec{R}'} T_{\vec{R}} \psi(\vec{r}) = C(\vec{R}') C(\vec{R}) \psi(\vec{r})$$

$$T_{\vec{R}+\vec{R}'} \psi(\vec{r}) = C(\vec{R}+\vec{R}') \psi(\vec{r})$$

$$\therefore C(\vec{R}+\vec{R}') = C(\vec{R}') C(\vec{R})$$

$$\therefore \vec{R} = n_1 \vec{a}_1 + n_2 \vec{a}_2 + n_3 \vec{a}_3, \quad \vec{a}_i = \text{primitive lattice vectors}$$

$$\therefore C(\vec{R}) = [C(\vec{a}_1)]^{n_1} [C(\vec{a}_2)]^{n_2} [C(\vec{a}_3)]^{n_3}$$

In addition $T_{-\vec{R}} = T_{\vec{R}}^+ \therefore C(-\vec{R}) = C(\vec{R})^*$

$$\therefore C(\vec{R}) C(-\vec{R}) = C(\vec{0}) = 1$$

$$\therefore |C(\vec{R})|^2 = 1$$

\therefore It's always possible to write

$$C(\vec{a}_i) = e^{2\pi i X_i} \quad X_i \text{ being some numbers}$$

$$\therefore C(\vec{R}) = e^{2\pi i (n_1 X_1 + n_2 X_2 + n_3 X_3)}$$

Let \vec{g}_i be reciprocal lattice vectors

$$\vec{g}_i \cdot \vec{a}_j = 2\pi \delta_{ij}$$

$$\therefore 2\pi (n_1 x_1 + n_2 x_2 + n_3 x_3)$$

$$= \underbrace{(n_1 \vec{a}_1 + n_2 \vec{a}_2 + n_3 \vec{a}_3)}_{\vec{R}} \cdot \underbrace{(x_1 \vec{g}_1 + x_2 \vec{g}_2 + x_3 \vec{g}_3)}_{\vec{k}}$$

$$\equiv \vec{R} \cdot \vec{R}$$

$$\therefore C(\vec{R}) = e^{i\vec{R} \cdot \vec{R}}$$

Hence $\psi(\vec{r} + \vec{R}) = T_{\vec{R}} \psi(\vec{r}) = e^{i\vec{R} \cdot \vec{R}} \psi(\vec{r})$
 there exists \vec{k} such that

Crystal momentum v.s. momentum

From the above derivation, it is clear that $\because [T_{\vec{R}}, H] = 0$

$C(\vec{R})$ is a constant of motion: $\frac{dC}{dt} = \frac{i}{\hbar} [T_{\vec{R}}, H] = 0$

\therefore what is conserved is $e^{i\vec{R} \cdot \vec{R}}$!

Hence $\hbar \vec{k}$ (for electronic systems) is not

the real momentum. Just as \vec{k} for phonons,

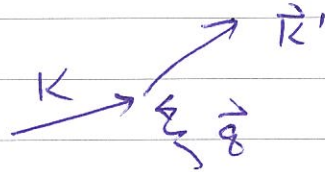
\vec{k} is termed as crystal momentum!

It is clear that $\psi_{\vec{k}}(\vec{r})$ is not an
 eigenstate to momentum:

$$\frac{\hbar}{i} \nabla \psi_{\vec{k}} = \frac{\hbar}{i} \nabla [e^{i\vec{k} \cdot \vec{r}} \psi_{\vec{k}}(\vec{r})] = \hbar \vec{k} \psi_{\vec{k}}(\vec{r}) + e^{i\vec{k} \cdot \vec{r}} \frac{\hbar}{i} \nabla \psi_{\vec{k}}(\vec{r})$$

As long as momentum conservation is concerned, one allows $\hbar\vec{G}$ difference and this is the umklapp process for electrons.

e.g. $\hbar\vec{k}' = \hbar\vec{k} + \hbar\vec{g} + \hbar\vec{G}$



Structure of reciprocal lattice

- The Bloch theorem implies that \vec{k} is a good label for electrons.

If we further impose the periodic boundary condition,

$$\psi(\vec{r} + N_i \vec{a}_i) = \psi(\vec{r}) \quad i=1, 2, 3$$

$$\therefore \psi(\vec{r} + N_i \vec{a}_i) = e^{i\vec{k} \cdot N_i \vec{a}_i} \psi(\vec{r})$$

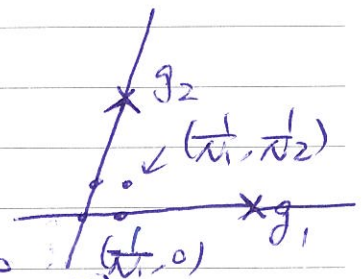
$$\therefore e^{i\vec{k} \cdot N_i \vec{a}_i} = 1 \quad \text{for } i=1, 2, 3$$

Therefore, if we write $\vec{k} = x_1 \vec{g}_1 + x_2 \vec{g}_2 + x_3 \vec{g}_3$,

$$\text{we get } 2\pi x_i N_i = 2\pi m_i$$

$$\therefore x_i = \frac{m_i}{N_i} \quad m_i = \text{integers}$$

$$\vec{k} = \frac{m_1}{N_1} \vec{g}_1 + \frac{m_2}{N_2} \vec{g}_2 + \frac{m_3}{N_3} \vec{g}_3$$



\therefore Each allowed \vec{k} occupies $\Delta^3 \vec{k} = \frac{\vec{g}_1}{N_1} \cdot \left(\frac{\vec{g}_2}{N_2} \times \frac{\vec{g}_3}{N_3} \right)$

$$\text{i.e. } \Delta^3 \vec{k} = \frac{1}{N} \vec{g}_1 \cdot (\vec{g}_2 \times \vec{g}_3)$$

Since the volume of a primitive cell of the reciprocal lattice = $\vec{g}_1 \cdot (\vec{g}_2 \times \vec{g}_3)$

\therefore # of allowed \vec{k} in a primitive cell of the reciprocal lattice = N = # of sites of the crystal!

Furthermore, because $\vec{g}_1 \cdot (\vec{g}_2 \times \vec{g}_3) = \frac{(2\pi)^3}{V}$, $V = \frac{V}{N}$

(using $\vec{g}_1 = 2\pi \frac{\vec{a}_2 \times \vec{a}_3}{\vec{a}_1 \cdot (\vec{a}_2 \times \vec{a}_3)}$, $\vec{g}_2 = 2\pi \frac{\vec{a}_3 \times \vec{a}_1}{\vec{a}_2 \cdot (\vec{a}_3 \times \vec{a}_1)}$,

$\vec{g}_3 = 2\pi \frac{\vec{a}_1 \times \vec{a}_2}{\vec{a}_3 \cdot (\vec{a}_1 \times \vec{a}_2)}$), we find

$$\Delta^3 \vec{k} = \frac{1}{N} \times \frac{(2\pi)^3}{V} = \frac{(2\pi)^3}{V}$$

Which is exactly the same form as that for free electrons.

$$\therefore \sum_{\vec{k}} F(\vec{k}) = \frac{V}{(2\pi)^3} \sum_{\vec{k}} F(\vec{k}) \Delta^3 \vec{k}$$

primitive cell

$$= V \int \frac{d^3 \vec{k}}{(2\pi)^3} F(\vec{k})$$

$$= V \int_0^1 \int_0^1 \int_0^1 \frac{dx_1 dx_2 dx_3}{(2\pi)^3} F(x_1 \vec{g}_1 + x_2 \vec{g}_2 + x_3 \vec{g}_3)$$

Energy bands

∴ For a given \vec{k} , $\hat{H} \psi_{\vec{k}} = \lambda \psi_{\vec{k}}$

In the case of electrons, we set $\psi_{\vec{k}} = e^{i\vec{k} \cdot \vec{r}} u_{\vec{k}}(\vec{r})$

$$\hat{H} \psi_{\vec{k}} = e^{i\vec{k} \cdot \vec{r}} \left[\frac{\hbar^2}{2m} \left(\frac{1}{i} \nabla + \vec{k} \right)^2 + U(\vec{r}) \right] u_{\vec{k}}(\vec{r})$$

∴ $u_{\vec{k}}(\vec{r})$ satisfies

$$\left[\frac{\hbar^2}{2m} \left(\frac{1}{i} \nabla + \vec{k} \right)^2 + U(\vec{r}) \right] u_{\vec{k}}(\vec{r}) = \epsilon u_{\vec{k}}(\vec{r}) \quad \text{--- (4)}$$

with the boundary condition $u_{\vec{k}}(\vec{r}) = u_{\vec{k}}(\vec{r} + \vec{R})$ --- (5)

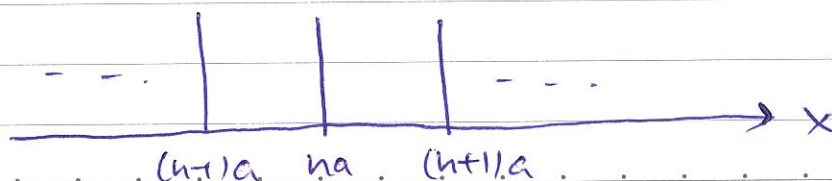
This is the remarkable advantage that the Bloch theorem implies: one only needs to solve the problem in a unit cell !!

It thus reduces the effort of dealing 10^{23} atoms in a crystal to the effort of dealing one!

As an example, we consider the classic example: periodic potential in 1D.

A Kronig-Penny model

$$U(x) = g \sum_{n=-\infty}^{\infty} \delta(x - na) \quad g > 0 \text{ (repulsive)}$$



Between $(n-1)a$ & na , $V=0$ \therefore \dots
 $\} na$ & $(n+1)a$

$\psi(x)$ is a combination of $e^{i\beta x}$ & $e^{-i\beta x}$.
 with $\frac{\hbar^2 \beta^2}{2m} = E$

We set

$$(n-1)a \leq x < na$$

$$\psi(x) = A_{n-1} e^{i\beta(x-na)} + B_{n-1} e^{-i\beta(x-na)}$$

$$na \leq x < (n+1)a$$

$$\psi(x) = A_n e^{i\beta(x-(n+1)a)} + B_n e^{-i\beta(x-(n+1)a)}$$

Boundary conditions at $x=na$

$$\psi(na^-) = \psi(na^+) \quad \dots (6)$$

$$\frac{d}{dx} \psi \Big|_{x=na^+} - \frac{d}{dx} \psi \Big|_{x=na^-} = \frac{2m}{\hbar^2} g \psi(na) \quad \dots (7)$$

(6), (7) implies

$$A_{n-1} + B_{n-1} = A_n e^{-i\beta a} + B_n e^{i\beta a}$$

$$i\beta (A_n e^{-i\beta a} - B_n e^{i\beta a}) - i\beta (A_{n-1} - B_{n-1}) = \lambda (A_{n-1} + B_{n-1})$$

Hence, we can write

$$\begin{pmatrix} 1 & 1 \\ 1+i\beta & 1-i\beta \end{pmatrix} \begin{pmatrix} A_{n-1} \\ B_{n-1} \end{pmatrix} = \begin{pmatrix} e^{-i\beta a} & e^{i\beta a} \\ i\beta e^{-i\beta a} & -i\beta e^{i\beta a} \end{pmatrix} \begin{pmatrix} A_n \\ B_n \end{pmatrix}$$

$$\therefore \begin{pmatrix} A_n \\ B_n \end{pmatrix} = T \begin{pmatrix} A_{n-1} \\ B_{n-1} \end{pmatrix} \quad T = \text{transfer matrix} \\ \text{(essentially translational operator)}$$

$$T = \begin{pmatrix} e^{-iqa} & e^{iqa} \\ +iqe^{-iqa} & -iqe^{iqa} \end{pmatrix}^{-1} \begin{pmatrix} 1 & 1 \\ \lambda + iq & \lambda - iq \end{pmatrix}$$

$$= \frac{-1}{2iq} \begin{pmatrix} -iqe^{iqa} & -e^{iqa} \\ -iqe^{-iqa} & e^{-iqa} \end{pmatrix} \begin{pmatrix} 1 & 1 \\ \lambda + iq & \lambda - iq \end{pmatrix}$$

$$= \frac{-1}{2iq} \begin{pmatrix} -2iqe^{iqa} - \lambda e^{iqa} & -\lambda e^{iqa} \\ \lambda e^{-iqa} & -2iqe^{-iqa} + \lambda e^{-iqa} \end{pmatrix}$$

Now, Bloch theorem implies $\psi(x+a) = \psi(x) e^{ika}$
for $(n-1)a < x < na$

$$\therefore A_n [e^{iqa(x+a-(n+1)a)} + e^{-iqa(x+a-(n+1)a)}] \\ = [A_{n-1} e^{iqa x} + B_{n-1} e^{-iqa x}] e^{ika}$$

$$\therefore A_n = e^{ika} A_{n-1}, \quad B_n = e^{ika} B_{n-1}$$

$$\begin{pmatrix} A_n \\ B_n \end{pmatrix} = e^{ika} \begin{pmatrix} A_{n-1} \\ B_{n-1} \end{pmatrix} \quad \dots \textcircled{2}$$

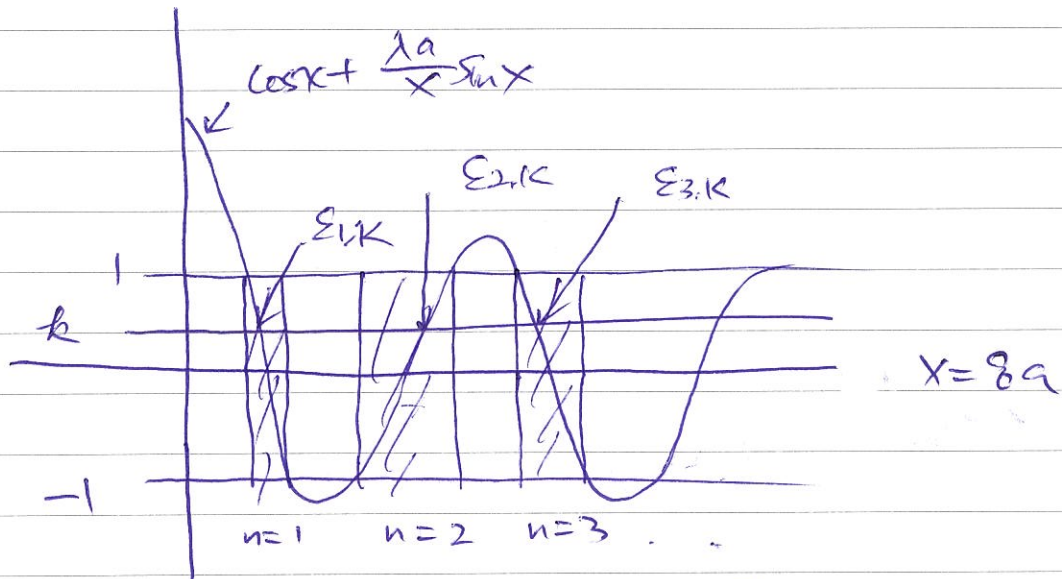
Eqs $\textcircled{1}$ & $\textcircled{2}$ ^{simply} implies the eigenvalue of T

is e^{ika} !

Similarly, the eigenvalue of T^{-1} is e^{-ika} !

From $\det(T - e^{iKa} \mathbb{1}) = 0$, one finds

$$\cos Ka = \cos \delta a + \frac{\lambda a}{2g} \sin \delta a$$



$\therefore -1 \leq \cos Ka \leq 1$, one sees that there are many allowed

$E = \frac{\hbar^2 k^2}{2m}$ for a given k . They can generally be labelled as $E_n(k)$.

As k varies, $E_n(k)$ changes continuously.

Therefore, they form so-called energy bands.

Furthermore, since only $\cos Ka$ matters, $k + G \neq k$ have the same value of $\cos ka$ ($G = \frac{2\pi m}{a}$).

$$E_n(k + G) = E_n(k) \quad \dots \quad (10)$$

For the wave function, Eq (9) implies

$$\psi_{k+G} = \psi_k \quad \text{--- (11)}$$

The meaning of eqs. (11) & (12) is that k is a label of electronic state, and

$k+G$ labels the same electronic state!

Fourier analysis One can understand this by

looking into the Fourier analysis of $\psi(\vec{r})$.

$$\text{In general, } \psi(\vec{r}) = \sum_{\vec{q}} \psi_{\vec{q}} e^{i\vec{q} \cdot \vec{r}} \quad (\text{no restriction on } \vec{q})$$

$$U(\vec{r}) = \sum_{\vec{G}} U_{\vec{G}} e^{i\vec{G} \cdot \vec{r}}$$

$$(\because U^*(x) = U(x) \therefore U_{\vec{G}}^* = U_{\vec{G}})$$

$$U(\vec{r}) \psi(\vec{r}) = \sum_{\vec{G}} \sum_{\vec{k}} U_{\vec{G}} \psi_{\vec{q}} e^{i\vec{G} \cdot \vec{r}} e^{i\vec{q} \cdot \vec{r}}$$

$$= \sum_{\vec{q}} \left[\sum_{\vec{G}} U_{\vec{G}} \psi_{\vec{q}-\vec{G}} \right] e^{i\vec{q} \cdot \vec{r}}$$

$$\vec{q} = \vec{q} + \vec{G}$$

$$\therefore \frac{\hbar^2}{2m} \nabla^2 \psi(\vec{r}) = \sum_{\vec{q}} \epsilon_{\vec{q}}^0 \psi_{\vec{q}} e^{i\vec{q} \cdot \vec{r}} \quad \epsilon_{\vec{q}}^0 = \frac{\hbar^2 q^2}{2m}$$

$$\therefore \hat{H}\psi = \epsilon\psi \Rightarrow \sum_{\vec{q}} \left[\epsilon_{\vec{q}}^0 \psi_{\vec{q}} + \sum_{\vec{G}} U_{\vec{G}} \psi_{\vec{q}-\vec{G}} \right] e^{i\vec{q} \cdot \vec{r}} = \epsilon \sum_{\vec{q}} \psi_{\vec{q}} e^{i\vec{q} \cdot \vec{r}}$$

$$\therefore (\epsilon_{\vec{q}}^0 - \epsilon) \psi_{\vec{q}} + \sum_{\vec{G}} U_{\vec{G}} \psi_{\vec{q}-\vec{G}} = 0$$

It is clear that for a given k , k only couples to $k \pm G$, $k \pm 2G$, $k \pm 3G$, ...

$$\text{Hence, } \psi(\vec{r}) = \sum_G \psi_{\vec{k}-G} e^{i(\vec{k}-G) \cdot \vec{r}} \quad \dots (12)$$

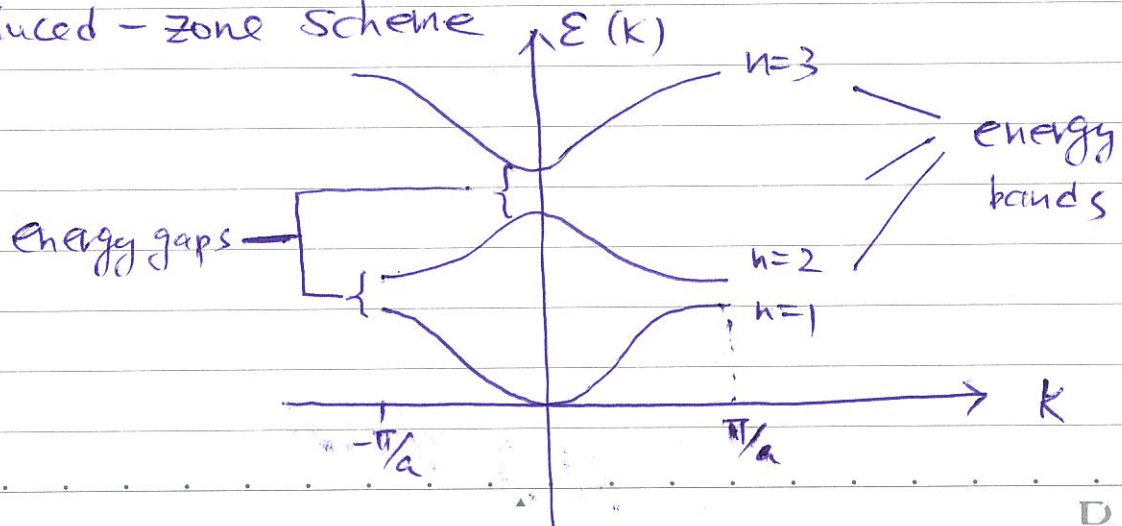
When one changes $\vec{k} \rightarrow \vec{k} + \vec{G}'$, it only shifts G to $G - G'$. Since G is a dummy variable, it describes the same wave function!

This is similar to the case of phonons. one can restrict the label of k to the 1st Brillouin zone or not restrict the label.

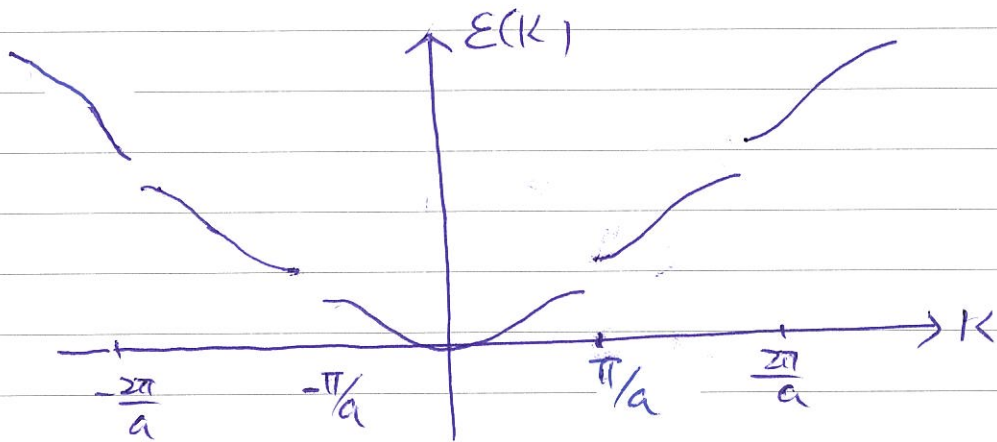
This results in 3 different ways of indexing (labeling) / describing the energy bands. Note that \vec{k} is only a label and it doesn't mean $\hbar\vec{k}$ is the momentum of the electrons.

Unlike phonons which doesn't have definition of real momentum, the electron's momentum can exceed the 1st Brillouin zone. In some sense, $\hbar(\vec{k} + \vec{G})$ has meaning it doesn't exist for phonons.

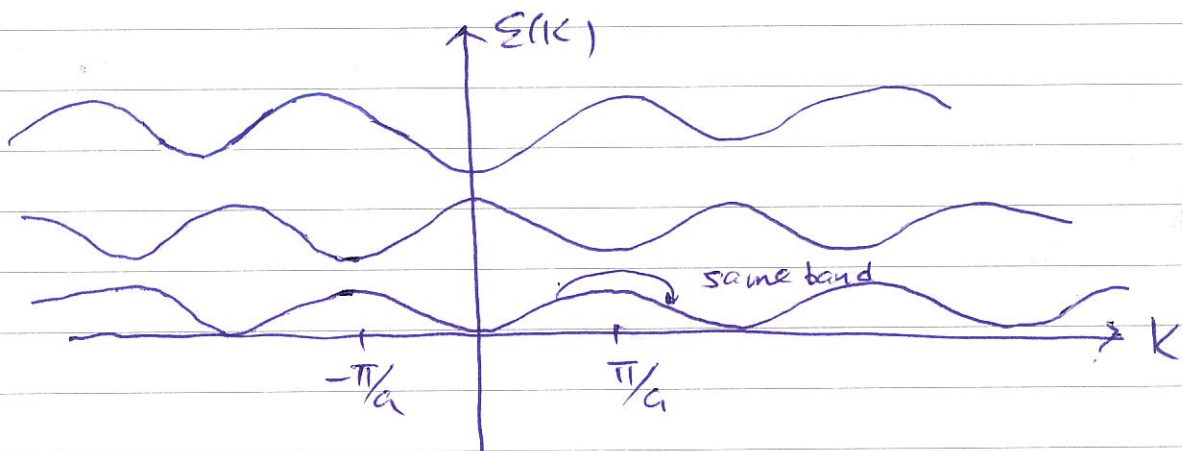
1. Reduced - zone scheme



2. extended - zone scheme



3. repeated - zone scheme



Density of states & Van Hove singularities

For many properties of crystals, it is the Energy, $E_n(k)$, that plays the dominant role.

It is therefore useful to define the

density of states (DOS) for the n th band

by $g_n(E) = \frac{2}{V} \sum_{\mathbf{k}} \delta(E - E_n(\mathbf{k}))$

$$= \frac{2}{V} \int \frac{d^3k}{(2\pi)^3} \delta(E - E_n(\mathbf{k}))$$

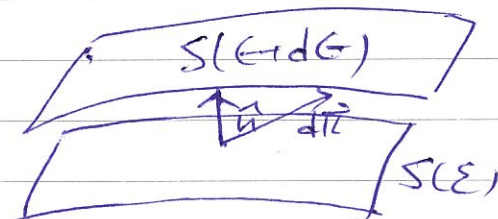
$g_n(\epsilon)$ can be casted into an integral over

the surface $E_n(k) = \epsilon$ by noting that

$$f(\epsilon - E_n(\vec{k})) = \frac{\theta(\epsilon - E_n(\vec{k})) - \theta(\epsilon - E_n(\vec{k}) - d\epsilon)}{d\epsilon}$$

$$\therefore d^d \vec{k} = dS(\epsilon) \cdot (d\vec{k} \cdot \hat{n})$$

$$\hat{n} = \frac{\vec{\nabla}_k E_n(\vec{k})}{|\vec{\nabla}_k E_n(\vec{k})|}$$



$$E_n(\vec{k} + d\vec{k}) = E_n(\vec{k}) + d\vec{k} \cdot \vec{\nabla}_k E_n(\vec{k}) \quad \therefore d\vec{k} \cdot \vec{\nabla}_k E_n(\vec{k}) = d\epsilon$$

$$\therefore d\vec{k} \cdot \hat{n} = \frac{d\epsilon}{|\vec{\nabla}_k E_n(\vec{k})|}$$

$$\int d\epsilon f(\epsilon - E_n(\vec{k})) = 1$$

$$\therefore g_n(\epsilon) = \frac{2}{(2\pi)^d} \int \frac{dS}{|\vec{\nabla}_k E_n(\vec{k})|} \Big|_{E_k = \epsilon} \quad \text{--- (12)}$$

$E_n(\vec{k})$ is periodic \vec{k} & bounded, there continuous,

must be points at which $|\vec{\nabla}_k E_n(\vec{k})| = 0$

max, min, saddle points!

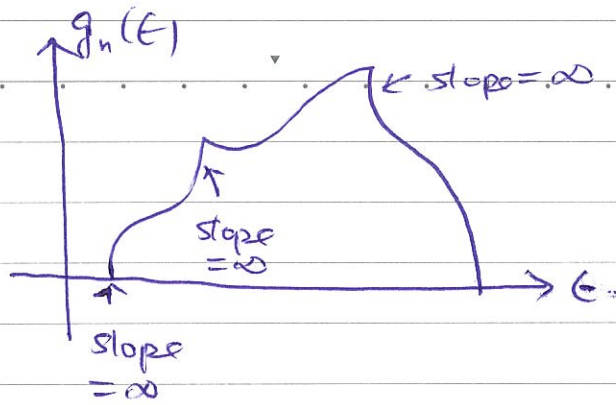
\therefore Integrand diverges in (12)

In 3D, these divergences are integrable (see

HW Ex 8-2), $g_n(\epsilon)$ is finite but

stages are infinite.

example

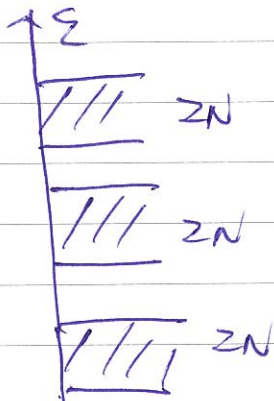


For 2D, $g_n(E) \sim \ln\left|\frac{E}{E_0} - 1\right|$ or $\Theta(\pm E)$

1D, $g_n(E) \sim \frac{1}{\sqrt{E}}$

Fermi energy, metals & insulators

As we have counted, # of k in a Brillouin zone = # of lattice points.

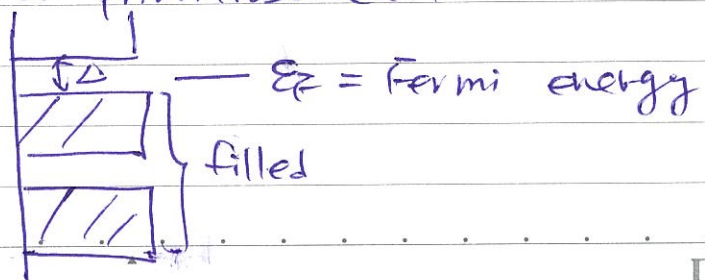


Therefore, including spin \uparrow & \downarrow , each band can hold $2N$ electrons!

Therefore, the most important aspect of lattice is the emergent properties of metals & insulators (band)

(i) # of electrons in a primitive cell

= e_{cell}



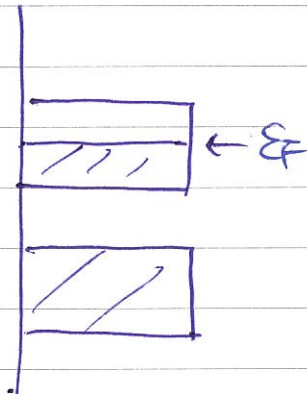
In this case, to excite the electron, one needs Δ . The system is gapped

(an energy of)

and is a band insulator. The Electric field can't excite the electron across the gap.

(ii) # of electrons in a primitive cell

= odd



The energy band that E_F cuts through is half-filled. Therefore, there is no energy gap to excite an electron. The system is a metal.

Mean velocity of electrons in periodic potential

Classically, ^{an} electron constantly collides with ions. Quantum mechanically, this is no longer true.

In fact, we find that the average velocity (momentum) for the Bloch state is

$$\begin{aligned}\vec{v}_n(\vec{k}) &= \frac{1}{\hbar} \vec{\nabla}_k \epsilon_n(\vec{k}) \\ &= \frac{1}{m} \int d^3r \psi_{n\vec{k}}^* \frac{\hbar}{i} \vec{\nabla} \psi_{n\vec{k}}\end{aligned}$$

To show it, we note that

$$\epsilon_n(\vec{k}+\vec{q}) = \epsilon_n(\vec{k}) + \vec{q} \cdot \vec{\nabla}_k \epsilon_n(\vec{k}) + O(q^2)$$

$$H_{\vec{k}+\vec{q}} = H_{\vec{k}} + \frac{\hbar^2}{m} \vec{q} \cdot \left(\frac{1}{i} \vec{\nabla} + \vec{k}\right) + \frac{\hbar^2 q^2}{2m}$$

$$\uparrow \quad \frac{\hbar^2}{2m} \left(\frac{1}{i} \vec{\nabla} + \vec{k}\right)^2 + U(\vec{r})$$

$$\left[\frac{\hbar^2}{2m} \left(\frac{1}{i} \vec{\nabla} + \vec{k} + \vec{q}\right)^2 + U(\vec{r}) \right] \psi_{n\vec{k}+\vec{q}}(\vec{r}) = \epsilon_{n\vec{k}+\vec{q}} \psi_{n\vec{k}+\vec{q}}(\vec{r})$$

\nwarrow linear
 \therefore The perturbation is $\hat{U} = \frac{\hbar^2}{m} \vec{q} \cdot \left(\frac{1}{i} \vec{\nabla} + \vec{k}\right)$

$$\begin{aligned}\text{Hence, } \vec{q} \cdot \vec{\nabla}_k \epsilon_n(\vec{k}) &= \int d^3r \psi_{n\vec{k}}^* \hat{U} \psi_{n\vec{k}} \\ &= \frac{\hbar^2}{m} \vec{q} \cdot \int d^3r \psi_{n\vec{k}}^* \left(\frac{1}{i} \vec{\nabla} + \vec{k}\right) \psi_{n\vec{k}}\end{aligned}$$

$$\therefore \vec{\nabla}_k \epsilon_n(\vec{k}) = \frac{\hbar^2}{m} \int d^3r \psi_{n\vec{k}}^* \left(\frac{1}{i} \vec{\nabla} + \vec{k}\right) \psi_{n\vec{k}}$$

$$\because \psi_{n\vec{k}} = e^{i\vec{k} \cdot \vec{r}} \psi_{n\vec{k}} \quad \therefore \left(\frac{1}{i} \vec{\nabla} + \vec{k}\right) \psi_{n\vec{k}} = e^{-i\vec{k} \cdot \vec{r}} \frac{1}{i} \vec{\nabla} \psi_{n\vec{k}}$$

$$\begin{aligned}\therefore \vec{\nabla}_k \epsilon_n(\vec{k}) &= \hbar \frac{1}{m} \int d^3r \psi_{n\vec{k}}^* \frac{1}{i} \vec{\nabla} \psi_{n\vec{k}} = \hbar \frac{\langle \vec{p} \rangle}{m} \\ &= \hbar \vec{v}_n(\vec{k})\end{aligned}$$

$$\therefore \vec{v}_n(\vec{k}) = \frac{1}{\hbar} \vec{\nabla}_k \epsilon_n(\vec{k})$$

This relation clearly implies that for ideal lattices, electrons can propagate with definite velocity. Therefore, $l = \infty$ which explains why l can be larger than the lattice spacing.

Symmetries of Schrödinger equation on a lattice

In addition to translational invariance, crystals also have discrete rotational symmetries (C_n) and etc summarize in the point group.

The translational invariance, summarized in the Bloch theorem, enables us to reduce the computational effort to a unit cell.

Do we have similar advantage in using point group symmetries?

* Symmetry points

First, the point group also acts on k so that there are special points in the k space.

Rotation on real space = inverse rotation

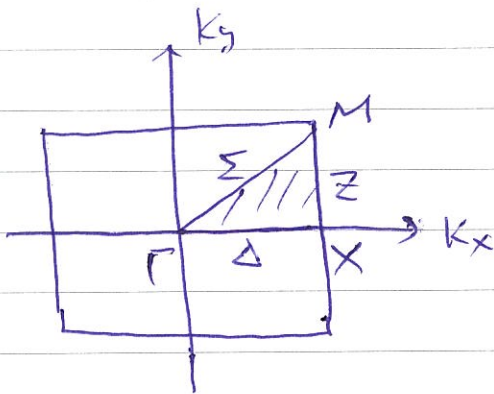
$$\text{On } k \text{ point: } \vec{R} \cdot \vec{R} \vec{v} = \vec{R}^T \vec{R} \vec{v} = (\vec{R}^T \vec{R})^T \cdot \vec{v} \\ = (\vec{R}^{-1} \vec{R}) \cdot \vec{v}$$

Therefore, under the group operation, the label k of the Bloch electron becomes $R^T k$!

There are special points that are invariant (up to a reciprocal lattice vector) under point group operations. For instance $\vec{k}=0$,

$R^T 0 = 0$. This is usually denoted by Γ point.

Take the square lattice as an example.



The point group is $4mm$

$$G = \{ E, R_1, R_2, R_3, R_4, m_x, m_y, m_+, m_- \}$$

mirror w.r.t. $x \pm y$ axes

The 1st Brillouin zone is shown in the above.

Γ is invariant under $G_\Gamma = G$

M is also invariant (up to a reciprocal lattice vector) $G_M = G_\Gamma = G$

$$G_X = \{ E, R_2, m_x, m_y \}$$

$$\overline{XM} = Z$$

$$\overline{TX} = \Delta, \quad G_\Delta = \{ E, m_x \}$$

$$G_Z = \{ E, m_y \}$$

$$\overline{TM} = \Sigma, \quad G_\Sigma = \{ E, m_+ \}$$

* $\Delta\Gamma X M$

To characterize (e.g. $\Sigma_n(k)$) the 1st Brillouin zone,

it is sufficient to characterize the region bounded by $\Gamma-X-M$.

$$\therefore H \psi_{\vec{k}} = \epsilon_{\vec{k}} \psi_{\vec{k}}$$

$$\Rightarrow g H g^{-1} \psi_{\vec{k}} = \epsilon_{\vec{k}} g \psi_{\vec{k}} \quad g \in G$$

Now, H is invariant under g

$$\therefore H g \psi_{\vec{k}} = \epsilon_{\vec{k}} g \psi_{\vec{k}} \quad \text{--- (13)}$$

In other words, $\psi_{\vec{k}}$, $g \psi_{\vec{k}}$ possess the

same $\epsilon_{\vec{k}}$. As already shown, $g \psi_{\vec{k}} = \psi_{g^{-1}\vec{k}}$

$$\therefore g \psi_{\vec{k}} = \psi_{\vec{k}'}, \quad \vec{k}' = g^{-1}\vec{k}$$

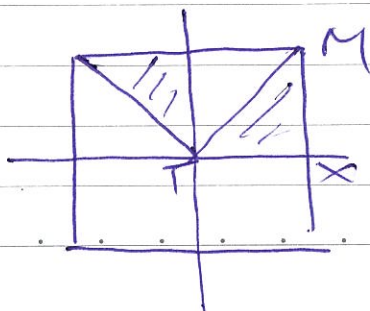
$$\therefore H \psi_{\vec{k}'} = \epsilon_{\vec{k}'} \psi_{\vec{k}'} \quad \text{--- (14)}$$

$$\therefore \epsilon_{\vec{k}'} = \epsilon_{\vec{k}}, \quad \text{i.e. } \epsilon_{g^{-1}\vec{k}} = \epsilon_{\vec{k}}$$

Example: $4mm$ (square lattice)

$$g = R_3, \quad g^{-1} = R_1, \quad g^{-1}\vec{k} = (-k_y, k_x)$$

$$\therefore \Sigma(k_x, k_y) = \Sigma(-k_y, k_x)$$



i.e. two triangles are

related to each other.

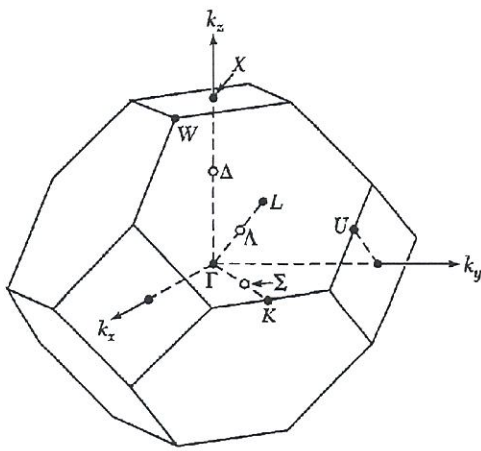
It's suffice to know $\epsilon_{\vec{k}}$ in $\Delta\Gamma X M$

One can convince himself that all other regions are related to $\Delta\Gamma X M$ by symmetries!

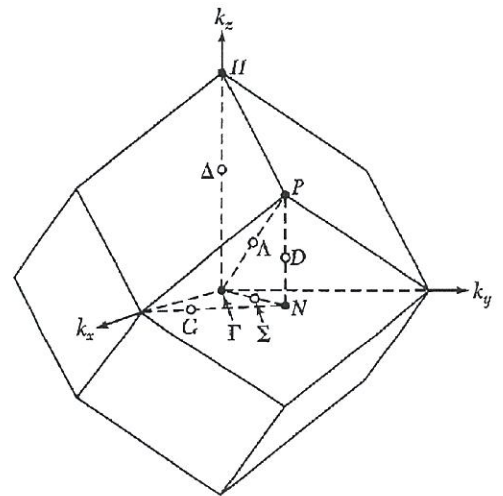
Therefore, it's suffice to know $E(k)$ in $\Delta\Gamma X M$.

Similar constructions apply to other crystals.

The followings are a couple of examples.



FCC



BCC

* Degeneracies of symmetry points

There is a tendency for $E(k)$ to be degenerate at symmetry points such as Γ , M & X . The

reason is that crystals possess both point group symmetry & translational symmetry.

For instance, Γ doesn't just represent $k=0$.

but it also represent $\vec{k} = \vec{0}, \pm \vec{b}, -\vec{b}, \dots$

Example: square lattice

$$\underbrace{\left(\frac{2\pi}{a}, 0\right)}_{G_1}, \quad \underbrace{\left(-\frac{2\pi}{a}, 0\right)}_{G_2}, \quad \underbrace{\left(0, \frac{2\pi}{a}\right)}_{G_3}, \quad \underbrace{\left(0, -\frac{2\pi}{a}\right)}_{G_4}$$

map into each other under C_{4mm} point operations of group.

$$\therefore \text{if } g \in C_{4mm} \quad gHg^{-1} = H$$

$$\therefore gHg^{-1}(g\psi_{G_i}) = \Sigma(g\psi_{G_i})$$

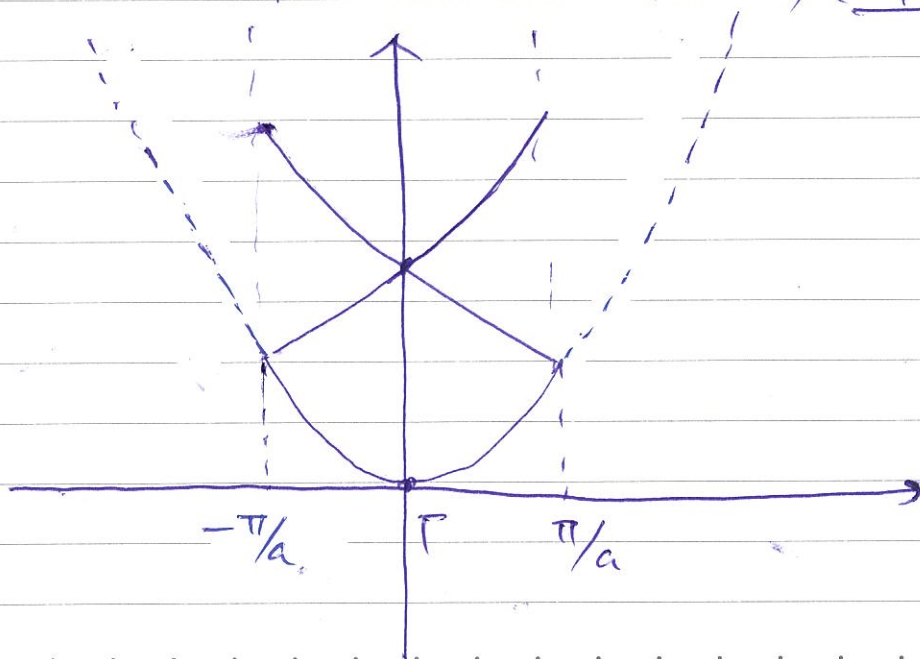
$$\therefore H(g\psi_{G_i}) = \Sigma(g\psi_{G_i})$$

$g\psi_{G_i} = \psi_{g^{-1}G_i}$ are degenerate with ψ_{G_i}

Since they are all labelled by $k=0, k=0$

is highly degenerate in Σ !

Example: 1D Simple lattice ($U=0$) (empty lattice)



Example: Empty lattice bands for 2D square lattice.

$$E_{n,m} = \frac{\hbar^2}{2m} (\vec{k} + \vec{G}_{nm})^2$$

$$\vec{G}_{nm} = \frac{2\pi}{a} (n\hat{x} + m\hat{y}), \quad \vec{k} \equiv \frac{2\pi}{a} (x, y)$$

$$\Psi_{nm}(\vec{k}, \vec{r}) = e^{i(\vec{k} + \vec{G}_{nm}) \cdot \vec{r}} \quad -\frac{1}{2} \leq x, y \leq \frac{1}{2}$$

$$E_{n,m} = \frac{\hbar^2}{2ma^2} [(x+n)^2 + (y+m)^2]$$

At Γ ($\vec{k}=0$): $E_{0,0} = 0$ $E_{1,\pm 1} = \frac{\hbar^2}{2ma^2} \times 2$

$E_{(0,\pm 1)} = E_{(\pm 1,0)} = \frac{\hbar^2}{2ma^2}$ $E_{-1,\pm 1} = \frac{\hbar^2}{2ma^2} \times 2$

At X ($\vec{k}=(1,0)$) $E_{0,0} = \frac{\hbar^2}{2ma^2} \times (\frac{1}{2})^2 = \frac{1}{4} \frac{\hbar^2}{2ma^2}$

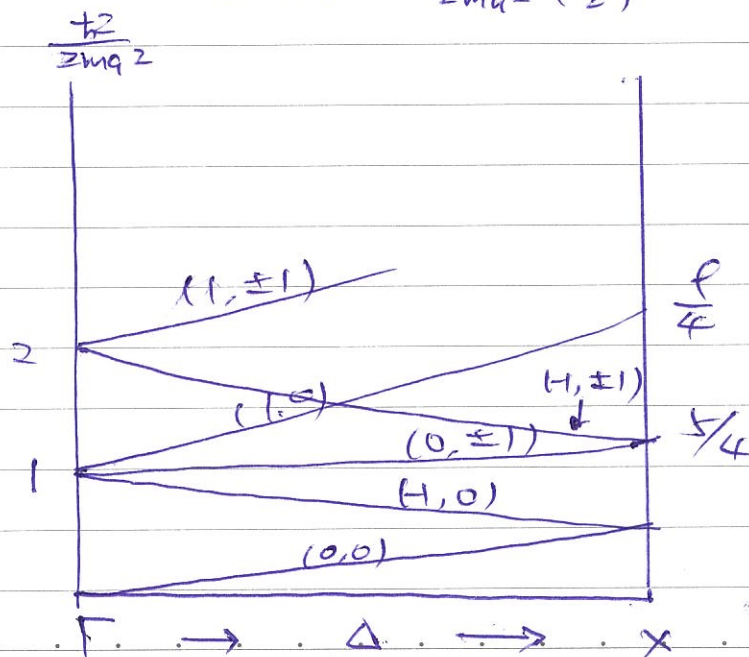
$E_{-1,0} = \frac{\hbar^2}{2ma^2} \times (-\frac{1}{2})^2 = \frac{1}{4}$ "

$E_{0,\pm 1} = \frac{\hbar^2}{2ma^2} [(\frac{1}{2})^2 + 1^2] = \frac{5}{4}$ "

$E_{-1,\pm 1} = \frac{\hbar^2}{2ma^2} [(-\frac{1}{2})^2 + 1^2] = \frac{5}{4}$ "

$E_{1,0} = \frac{\hbar^2}{2ma^2} (\frac{3}{2})^2$

We find



* Irreducible representations & reduction of computational effort

It is well known that in quantum mechanics, if one finds another operator (observable \hat{O}) that commutes with \hat{H} , one can save the computational effort by restricting us to the simultaneous eigenvalue spaces.

For instance, $[\hat{H}, L^2] = 0$, $[\hat{H}, L_z] = 0$

$L_z = z$ component of angular momentum

$L^2 =$ square of angular momentum

Hence, L_z , L^2 & H can be diagonalized simultaneously. Since the eigenfunctions to L_z & L^2 is $Y_l^m(\theta, \phi)$, if we use these eigenfunctions as basis in (θ, ϕ) , H is ^{to expand H} block diagonalized:

$$\begin{pmatrix} \boxed{l=1} & 0 & \dots & 0 & 0 \\ 0 & \boxed{l=2} & \begin{pmatrix} 2l+1 \\ 0 \end{pmatrix} & 0 \\ 0 & \begin{pmatrix} 2l+1 \\ 0 \end{pmatrix} & \boxed{l=3} & 0 \\ 0 & 0 & 0 & \dots \end{pmatrix} D$$

In other words, $\langle e | H | e' \rangle \propto \delta_{ee'}$, different matrix elements of

$l=0$! Hence rotational symmetries

reduce the computational effort to each

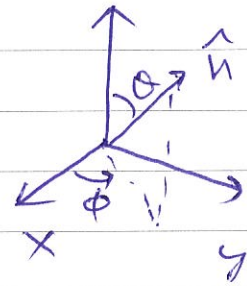
block of a $(2l+1)(2l+1)$ matrix!

Similar reduction also exists for point groups.

In this case, one needs to find representations of group elements first. In the case of continuous

rotations, the group element is

$$R(\theta, \hat{n}) = e^{\frac{i}{\hbar} \vec{J} \cdot \hat{n} \theta}$$



where \hat{n} is the axis of rotation.

$\vec{J} = \vec{L}$ if there is no spin.

Using $Y_{lm}(\theta, \phi)$, $R =$

$$\begin{pmatrix} \boxed{l=1} & 0 & 0 \\ 0 & \boxed{l=2} & 0 \\ 0 & 0 & \boxed{l=3} \end{pmatrix}$$

is also block diagonalized!

Therefore, we have to represent elements of the point group in terms of matrices. This is termed as representation of the group.

Irreducible representation of point groups

A representation is reducible if the corresponding matrices can be brought

into the block diagonal by choosing appropriate basis. Otherwise, it is

irreducible. For rotational groups, the

$(2l+1) \times (2l+1)$ blocks ^{in $R(E, \Phi)$} can't be reduced

further, they are irreducible.

Two useful theorems:

(1) # of irreducible representations (IRs)

= # of conjugate classes

a class = subset of a group in which

$R' = ARA^{-1}$. $A, R, R' \in$ the same subset.

Example: $4mm$.

Classes (1) E (2) $R_{\pi/2}, R_{3\pi/2}$ (3) R_{π} } \therefore # of IRs
 (4) m_x, m_y (5) i, σ_h } = 5.
 $\Gamma_1, \Gamma_2, \Gamma_3, \Gamma_4, \Gamma_5$

(ii) For i th IRs, $l_i = \text{dimension (of the matrix)}$, $\sum_i l_i^2 = \# \text{ of group elements}$

example: $4mm \Rightarrow l_1, l_2, l_3, l_4, l_5$

$$l_1^2 + l_2^2 + l_3^2 + l_4^2 + l_5^2 = 8$$

\therefore only $1^2 + 1^2 + 1^2 + 1^2 + 2^2 = 8$ is possible

\therefore 4 IRs \Rightarrow 1 dimension

1 IRs \Rightarrow 2x2 matrix

Basis functions

To represent point groups by matrices, one needs to choose basis functions.

Usually, one chooses polynomials of x, y, z as basis functions.

example: $4mm$

In $4mm$, x always $\rightarrow \pm x$, or $\pm y$

	E	R_π	$R_{\pi/2}$	$R_{-\pi/2}$	m_x	m_y	m_+	m_-
x	x	-x	y	-y	x	-x	y	-y
y	y	-y	-x	x	-y	y	x	-x

IR Γ_1

$$\psi_0 = x^2 + y^2$$

$$D(E) = D(R_\pi) = D(R_{\pi/2}) = D(R_{-\pi/2}) = D(m_x) =$$

$$= D(m_y) = D(m_+) = D(m_-) = 1$$

IR Γ_4

$$\psi_4 = xy$$

$$D(E) = D(R_\pi) = D(m_+) = D(m_-) = 1$$

$$D(R_{\pi/2}) = D(R_{-\pi/2}) = D(m_x) = D(m_y) = -1$$

These are usually summarized in the group table:

	$\psi_0 = x^2 + y^2$ D_{Γ_1}	$\psi_2 = xy(x^2 - y^2)$ D_{Γ_2}	$\psi_3 = x^2 - y^2$ D_{Γ_3}	$\psi_4 = xy$ D_{Γ_4}	$\psi_5 = \begin{pmatrix} x \\ y \end{pmatrix}$ D_{Γ_5}
E	1	1	1	1	$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$
R_π	1	1	1	1	$\begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$
$R_{\pi/2}$	1	1	-1	-1	$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$
$R_{-\pi/2}$	1	1	-1	-1	$\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$
m_x	1	-1	1	-1	$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$
m_y	1	-1	1	-1	$\begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$
m_+	1	-1	-1	1	$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$
m_-	1	-1	-1	1	$\begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}$
	$l_1 = 1$	$l_2 = 1$	$l_3 = 1$	$l_4 = 1$	$l_5 = 2$

The basis functions are ^{convenient} choices by one's construction.

They are not unique, hence IRs are not unique.

Using these basis functions, one can rewrite

\hat{H} , \hat{H} will be block diagonalized.

However; to apply this to energy bands,

one needs to combine the point group

with the translational operations, summarized

by \vec{k} !

As we have seen, not all of \vec{k} 's are invariant (up to reciprocal lattice vectors) under operations of point group.

Hence, using point group to reduce the

computational effort only restrict to

symmetry points (such as Γ , X, M, ...)

In this case, basis functions are also

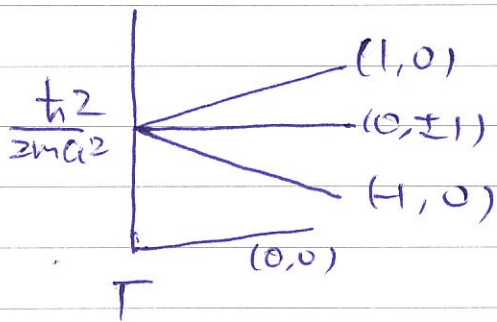
chosen differently by taking \vec{k} into

considerations!

As an example, we shall consider the

T point of the square lattice.

As we have seen, when $U=0$,



$$\psi = e^{i \vec{G}_{nm} \cdot \vec{r}}$$

$$\vec{G}_{nm} = \frac{2\pi}{a} (n, m)$$

$\therefore \psi_{00}(\vec{r}) = 1$ is a choice of basis functions.

\Rightarrow This is IR Γ_1 , all elements $\Rightarrow 1$

For $E = \frac{\hbar^2}{2ma^2}$, one has

$$\psi_{\pm 1, 0} = e^{\pm \frac{2\pi i}{a} x}$$

$$\psi_{0, \pm 1} = e^{\pm \frac{2\pi i}{a} y}$$

Hence, to analyze effects due to $U \neq 0$, ^{Small}

it's convenient to use $\psi_{\pm 1, 0}$ & $\psi_{0, \pm 1}$

to construct basis functions.

!! Under $4mm$, $x \rightarrow \pm x$, or $\pm y$
 $y \rightarrow \pm x$ or $\pm y$

Clearly, from combinations of $\psi_{\pm 1, 0}$, $\psi_{0, \pm 1}$, one has

$$\text{IR } \Gamma_1 : \psi_0 = x^2 + y^2 \Rightarrow \psi(\Gamma_1) = \cos \frac{2\pi x}{a} + \cos \frac{2\pi y}{a}$$

$$\propto \psi_{1,0} + \psi_{-1,0} + \psi_{0,1} + \psi_{0,-1}$$

$$\psi(\tau_3) = \cos \frac{\pi x}{a} - \cos \frac{\pi y}{a} \propto \psi_{1,0} + \psi_{1,0} - \psi_{0,1} - \psi_{0,1}$$

$$\psi(\tau_5) = \begin{pmatrix} \sin \frac{\pi x}{a} \\ \sin \frac{\pi y}{a} \end{pmatrix} \propto \begin{pmatrix} \psi_{1,0} - \psi_{-1,0} \\ \psi_{0,1} - \psi_{0,-1} \end{pmatrix}$$

Therefore, to investigate effect of U

set $\Sigma \approx \frac{\hbar^2}{2m a^2}$, $k=0$, one only needs to

consider $\psi(\tau_1)$, $\psi(\tau_3)$ & $\psi(\tau_5)$
 \downarrow
 $|1, \tau_1\rangle$
 & $\psi_{00}(\tau_1) (=1)$
 \downarrow
 $|0, \tau_1\rangle$

Using these basis functions, computational effort is reduced as one can see in below:

To solve $\hat{H}|\psi\rangle = \Sigma|\psi\rangle \quad \dots (15)$

one expand $|\psi\rangle = \sum_n |n\rangle \langle n|\psi\rangle$

$\langle n|(15)$

$$\sum_n \underbrace{\langle n|\hat{H}|m\rangle}_{H_{nm}} \underbrace{\langle m|\psi\rangle}_{\psi_m} = \Sigma \langle n|\psi\rangle$$

$$\underbrace{\begin{pmatrix} H_{11} & H_{12} & H_{13} & \dots \\ H_{21} & H_{22} & \dots \\ H_{31} & H_{32} & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}}_{\hat{H}} \begin{pmatrix} \psi_1 \\ \psi_2 \\ \vdots \end{pmatrix} = \Sigma \begin{pmatrix} \psi_1 \\ \psi_2 \\ \vdots \end{pmatrix}$$

At $k=0$, we use $\begin{pmatrix} \psi_0(\Gamma_1) \\ \psi_1(\Gamma_1) \\ \psi_1(\Gamma_3) \\ \psi_1(\Gamma_5) \\ \vdots \end{pmatrix}$, $\hat{H} = \frac{p^2}{2m} + U$

$$\hat{H} = \begin{pmatrix} \epsilon_0(\Gamma_1) & \langle 0\Gamma_1 | U | 1\Gamma_1 \rangle & \langle 0\Gamma_1 | U | 1\Gamma_3 \rangle & \langle 0\Gamma_1 | U | 1\Gamma_5 \rangle & \dots \\ \langle 1\Gamma_1 | U | 0\Gamma_1 \rangle & \epsilon_1(\Gamma_1) & \langle 1\Gamma_1 | U | 1\Gamma_3 \rangle & \langle 1\Gamma_1 | U | 1\Gamma_5 \rangle & \dots \\ \langle 1\Gamma_3 | U | 0\Gamma_1 \rangle & \langle 1\Gamma_3 | U | 1\Gamma_1 \rangle & \epsilon_1(\Gamma_3) & \langle 1\Gamma_3 | U | 1\Gamma_5 \rangle & \dots \\ \langle 1\Gamma_5 | U | 0\Gamma_1 \rangle & \langle 1\Gamma_5 | U | 1\Gamma_1 \rangle & \langle 1\Gamma_5 | U | 1\Gamma_3 \rangle & \epsilon_1(\Gamma_5) & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

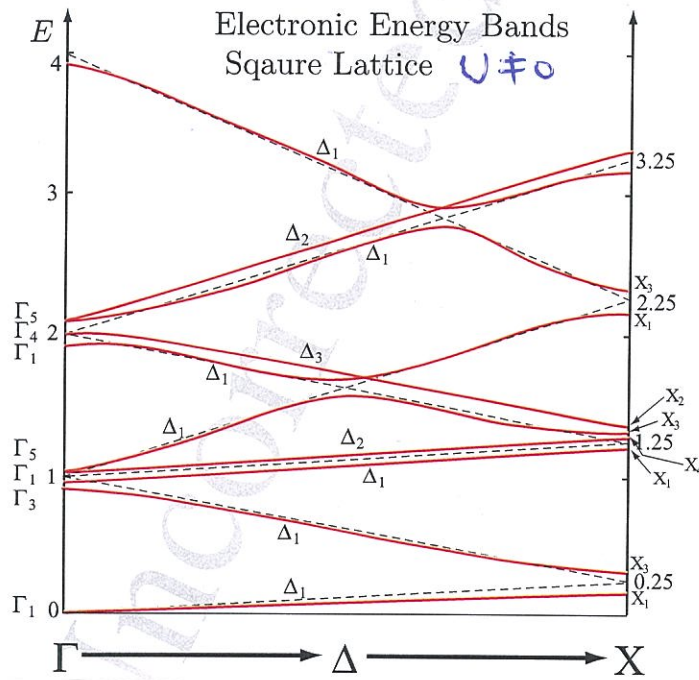
\Downarrow reduces to $\epsilon_0(\Gamma_1) = 0, \epsilon_1(\Gamma_1) = \frac{\hbar^2}{2ma^2}$

$$\hat{H} = \begin{pmatrix} \epsilon_0(\Gamma_1) & \langle 0\Gamma_1 | U | 1\Gamma_1 \rangle & 0 & 0 & \dots \\ \langle 0\Gamma_1 | U | 1\Gamma_1 \rangle & \epsilon_1(\Gamma_1) & 0 & 0 & \dots \\ 0 & 0 & \epsilon_1(\Gamma_3) & 0 & \dots \\ 0 & 0 & 0 & \epsilon_1(\Gamma_5) & \dots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

elements between different representations = 0!

Hence at symmetry points, different IRs of point groups are block diagonalized.

Solving the corresponding determinant, one finds



Clearly, we have seen that translational invariance & point group symmetry have strong effects on electronic states. This, of course, does not restrict to electronic states. E.M. waves & sound waves are also subjected to the same effects.