

Chapter 7 Work and Energy

In principle, all problems in classical mechanics can be solved by using Newton's laws.

In practice, we often have little information on the forces involved in a given situation.

Therefore, we introduce **a different approach** to the solution of problems in mechanics that is based on the concepts of **work** and **energy**.

Although energy can change form, it can be neither created nor destroyed. This is called the **principle of conservation of energy**.

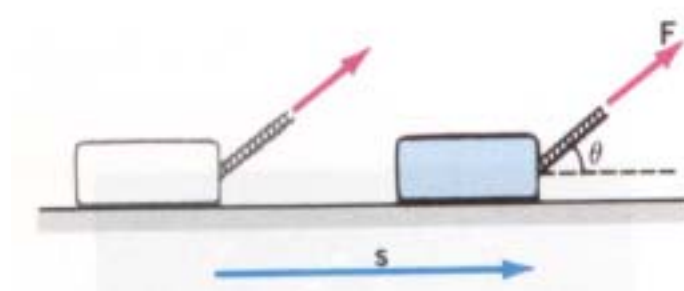
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7.1 Work Done by a Constant Force

The work **W** done by a constant force **F** when its point of application undergoes a displacement **s** is defined to be

$$W = Fs \cos \theta = \vec{F} \cdot \vec{s}$$

where θ is the angle between **F** and **s**.

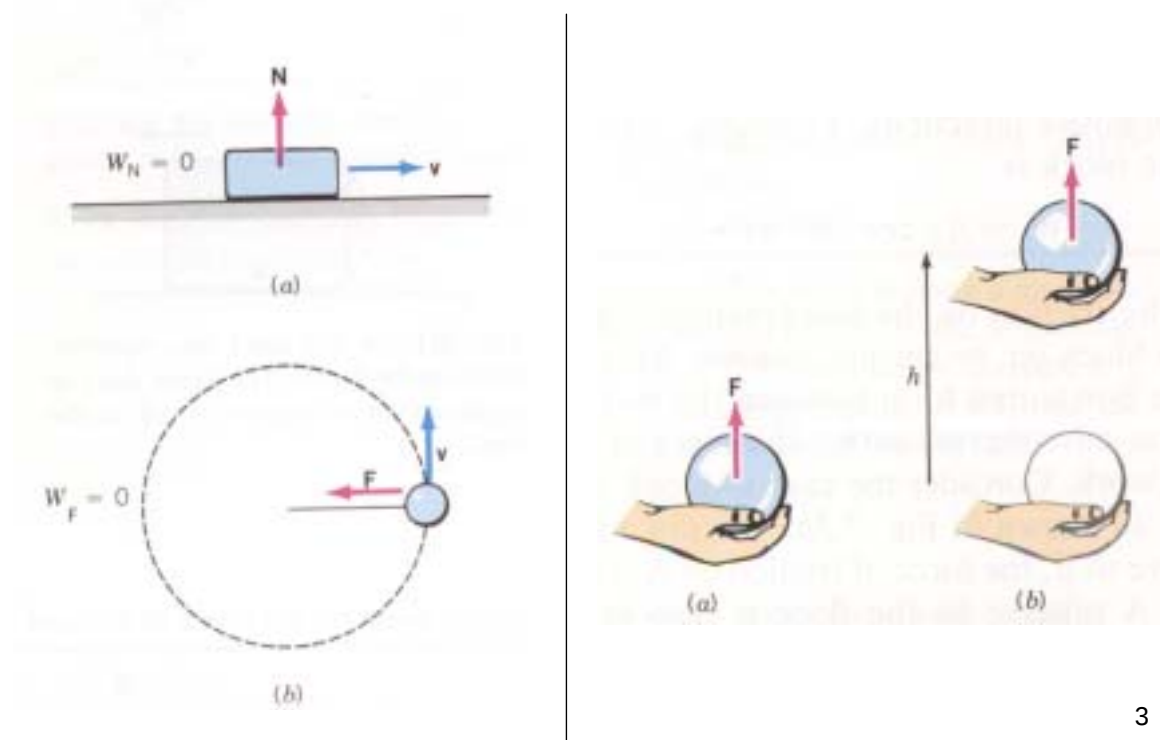


Work is a scalar quantity and its SI unit is joule (J).

$$1 \text{ J} = 1 \text{ N} \cdot \text{m}$$

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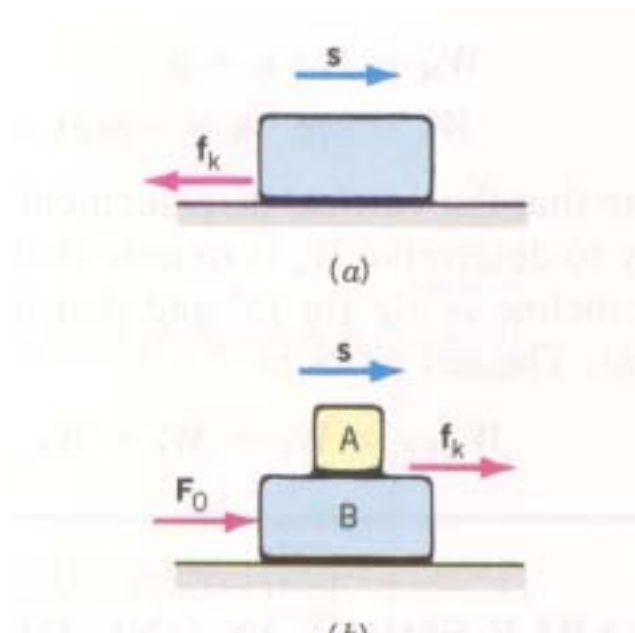
7.1 Work Done by a Constant Force: examples



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Negative Work and Work Done by Friction

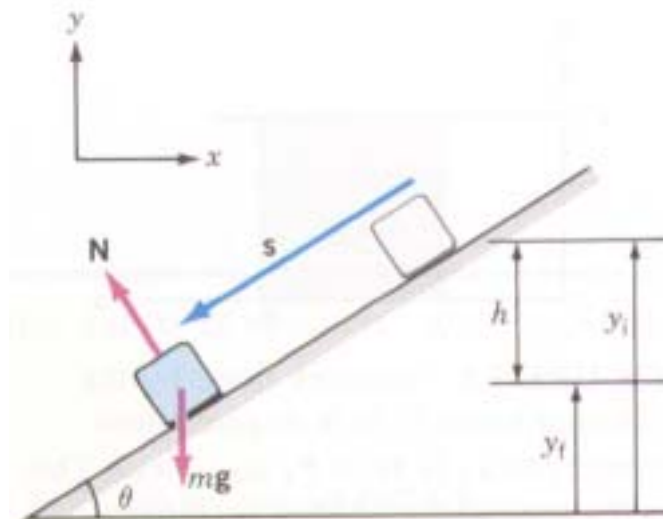
The force of kinetic (sliding) friction always does negative work is a common misconception.



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Work Done by Gravity

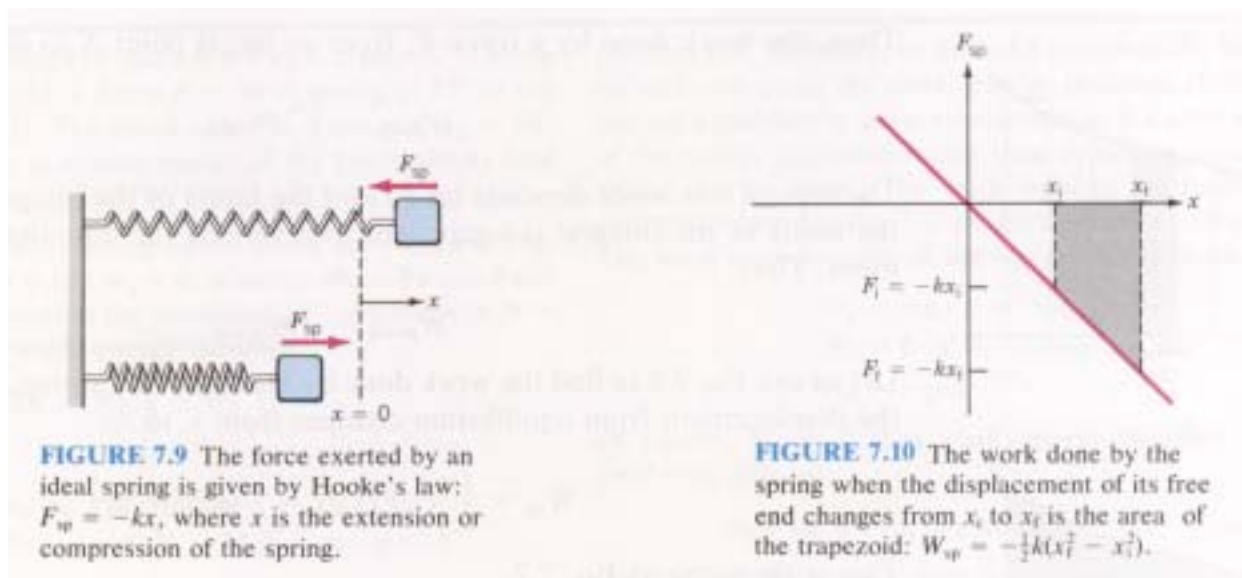
The work done by the force of gravity depends only on the **initial** and **final** vertical coordinates, *not on the path taken*. This is because the gravitation is a **conservative force**.



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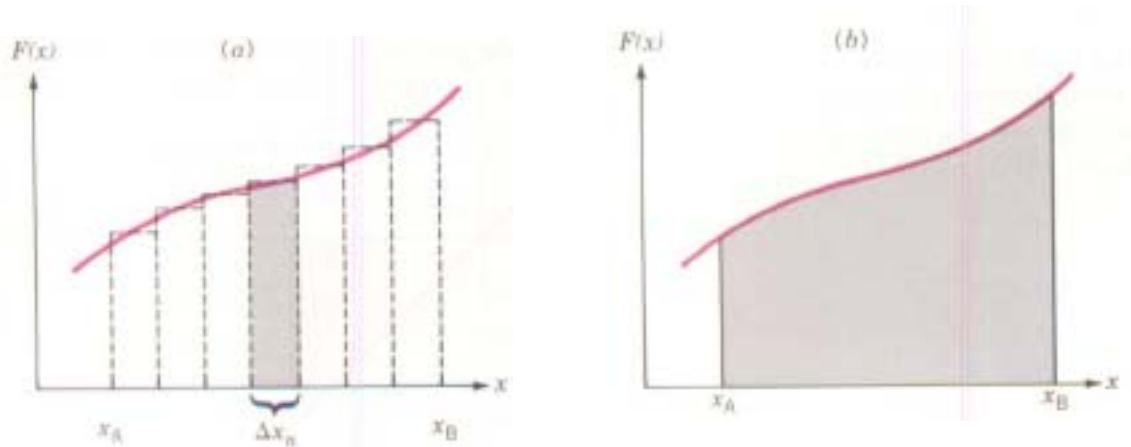
7.2 Work by a Variable Force in One Dimension

Work done by a spring: Hooke's law



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Work as an Integral of the F_x versus x Graph



$$W = \lim_{\Delta x_n \rightarrow 0} \left(\sum F_n \cdot \Delta x_n \right) = \int F_x dx$$

Thus, the work done by a force F_x from an initial point A to final point B is

$$W_{A \rightarrow B} = \int_{x_A}^{x_B} F_x dx$$

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7.3 Work-Energy Theorem in One Dimension

Work-energy theorem states that the net work done on a particle is equal to the resulting change in its (translational) kinetic energy.

$$W_{net} = \Delta K$$

Whereas **force** and **acceleration** are **vectors**, **work** and **energy** are **scalars**, which make them easier to deal with.

True/false: If the kinetic energy of a body is fixed, the net force on it is zero. Explain your response.

7.4 Power

Mechanical power is defined as the rate at which work is done.

Average Power $P_{av} = \frac{\Delta W}{\Delta t}$

Instantaneous Power $P = \lim_{\Delta t \rightarrow 0} \frac{\Delta W}{\Delta t} = \frac{dW}{dt}$

The instantaneous **mechanical power** may be written as

$$P = \frac{dW}{dt} = \vec{F} \cdot \vec{v}$$

The horsepower (hp), another unit of power, 1 hp=760 W

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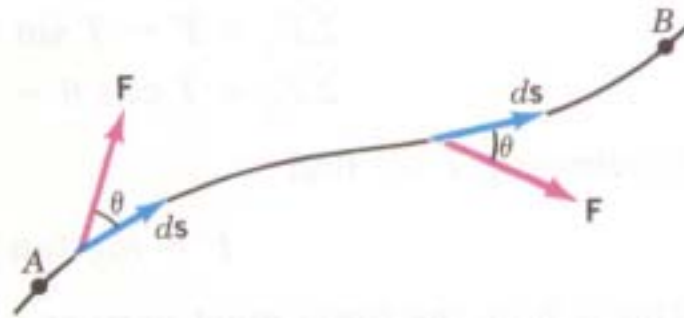
Tables of Energies and Powers

TABLE OF ENERGIES (J)		TABLE OF POWERS (W)	
Supernova explosion	10^{44}	Quasar (3C273)	4×10^{40}
Annual solar output	1.2×10^{34}	Solar output	4×10^{26}
Rotational energy of earth	2×10^{29}	Solar power incident	
Initial fossil fuels (ca. 1800)	2×10^{23}	on earth	1.74×10^{17}
Annual global use	2.7×10^{20}	U.S. consumption	2.7×10^{12}
Annual loss tidal friction	10^{20}	Photosynthesis (global)	4×10^{12}
Annual U.S. consumption	5×10^{19}	Hydroelectric (potential)	3×10^{12}
One megaton explosion	4.2×10^{15}	Tidal friction loss	3×10^{12}
Annual output of power station	10^{16}	Tidal power in use	7×10^{10}
Lightning flash	5×10^9	Geothermal power in use	1.5×10^9
One (U.S.) gallon of gasoline	1.3×10^8	Grand Coulee Dam	6.5×10^9
Daily intake of a person	1.3×10^7	Boeing 747	1.4×10^8
Proton in supercollider	3×10^{-7}	Aircraft carrier	1.2×10^8
Fission of uranium nucleus	3×10^{-11}	Locomotive	3×10^6
Proton in nucleus	10^{-13}	Powerful laser	10^6
Hydrogen bond	6×10^{-18}	Automobile	10^5
Minimum detectable by eye	3×10^{-18}	Radio transmitter	5×10^4
Electron in atom	10^{-18}	Human output	
Kinetic energy of molecule at		(short duration)	2×10^3
room temperature	10^{-21}	Person (resting)	75

7.5 Work and Energy in Three Dimension

When the magnitude and direction of a force vary in three dimensions, it can be expressed as a function of the position vector $\mathbf{F}(\mathbf{r})$, or in terms of the coordinates $\mathbf{F}(x, y, z)$.

$$\begin{aligned} W_{A \rightarrow B} &= \int_A^B \vec{F} \cdot d\vec{s} = \int_A^B F \cos \theta \, ds \\ &= \int_{x_A}^{x_B} F_x \, dx + \int_{y_A}^{y_B} F_y \, dy + \int_{z_A}^{z_B} F_z \, dz \end{aligned}$$



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Questions

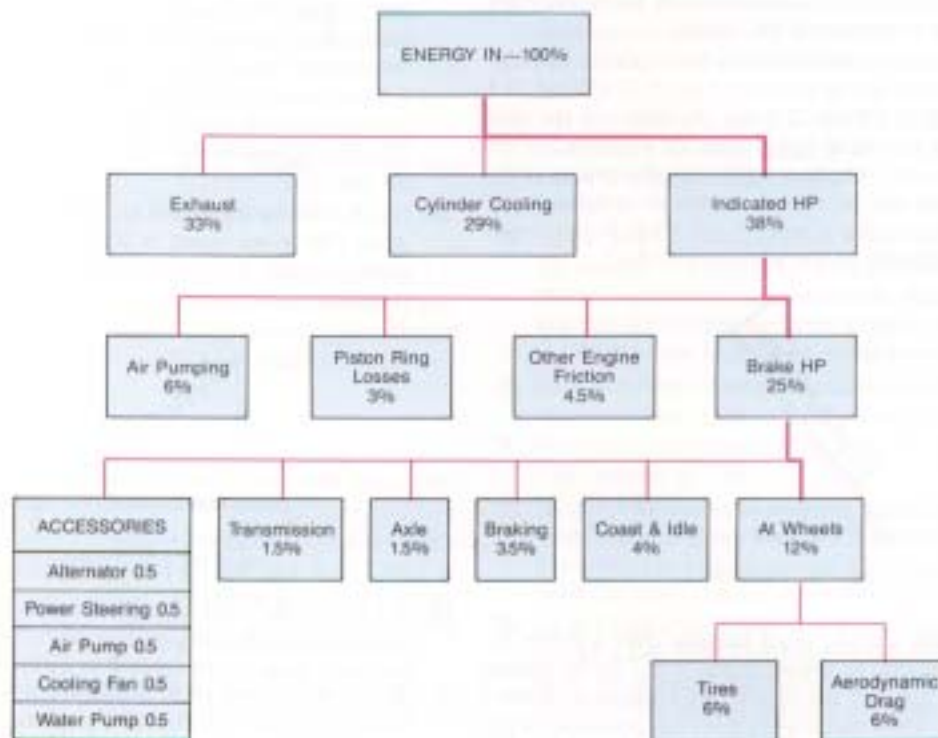
Do devices such as levers, pulleys, and gears, which allow us to use small forces, also save us work? Explain.

Compare the work done by a person who rises at constant velocity from the ground to the first floor (a) by using the stairs, and (b) by climbing a rope. Does the amount of energy he expends depend on the method?

Can work be done (a) by the force of static friction, or (b) by a centripetal force?

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Special Topic: Energy and the Automobile (I)



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Special Topic: Energy and the Automobile (II)

These large losses can be reduced in several ways.

- ◆ Drive at lower speeds to reduce aerodynamic drag and rolling resistance
- ◆ Modify the shape to be streamline to reduce aerodynamic drag
- ◆ Close the window to minimize the drag
- ◆ Maintain high tires pressures to minimize rolling resistance

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Exercises and Problems

Ch.7: Ex.33, 37, 41

Prob. 3, 5, 8, 9