# Chap. 9 Theory and Design of Ferrimagnetic Components

Basic Phenomena

9.1 Basic Properties of Ferrimagnetic Materials

- 9.2 Plane Wave Propagation in a Ferrite Medium
- 9.3 Propagation in a Ferrite-Loaded Rectangular Waveguide

#### **Applications**

9.5 Ferrite Phase Shifters

9.6 Ferrite Circulator/Isolator

#### Introduction to ferrite materials



The ferrites are crystals having small electric conductivity compared to ferromagnetic materials,

Thus they are useful in high-frequency situations because of the absence of significant eddy current losses.

## Properties of ferrite materials (I)

**Nonreciprocal electrical property**: the transmission coefficient through the device is not the same for different direction of propagation.

**Unequal propagation constant**: The left and right circularly polarized waves have different propagation constant along the direction of external magnetic field  $B_0$ .

**Anisotropic magnetic properties**: The permeability of the ferrite is not a single scalar quantity, but instead is a tensor, which can be represented as a matrix.

#### Properties of ferrite materials (II)

Ferrites are **ceramiclike materials** with *specific resistivities* that may be as much as  $10^{14}$  greater than that of metals and with *dielectric constants* around 10 to 15 or greater.

Ferrites are made by sintering a mixture of metal oxides and have the general chemical composition  $MO \cdot Fe_2O_3$ , where M is a divalent metal such as Mn, Mg, Fe, Zn, Ni, Cd, etc.

Relative permeabilities of **several thousand** are common. The magnetic properties of ferrites arise mainly from the **magnetic dipole moment** associated with the **electron spin**.

Classical picture of the magnetization process --- By treating the spinning electron as a gyroscopic top.

If an electron is located in a uniform static magnetic field  $\mathbf{B}_{0}$ , a torque is given by

$$T = m \times B_0 = -\mu_0 \gamma s \times H_0$$

$$T = \frac{ds}{dt} = \frac{-1}{\gamma} \frac{dm}{dt} \implies \frac{dm}{dt} = -\mu_0 \gamma m \times H_0$$
where  $\omega_0 = \frac{eB_0}{m_e}$  is called the Larmor fequency;  
 $s = \frac{\hbar}{2}$  is spin angular momentum;  
 $m = \frac{e}{m_e} \frac{\hbar}{2} = -\gamma s$  is magnetic dipole moment

## Quantum mechanics' viewpoint $s_z = \pm 1/2$

In the absence of any damping forces, the actual precession angle will be determined by the initial position of the magnetic dipole, and the dipole will precess about  $\mathbf{B}_0$  at this angle indifferently (free precession).

In reality, however, the existence of damping forces will cause the magnetic dipole *to spiral in* from its initial angle until **m** is aligned with  $\mathbf{B}_{0}$ .

This explains why  $s_z$  equals  $\pm 1/2$  in the Quantum Mechanics. But where does the damping force come from?

#### Saturation magnetization



As the strength of the bias field  $H_0$ is increased, more magnetic dipole moments will align with  $H_0$  until all are aligned, and M reaches an upper limit.

The material is then said to be magnetically saturated, and  $M_s$  is denoted as the saturation magnetization.  $M_s$  typically ranges from  $4\pi M_s$ =300 to 5000 Gauss.

Below saturation, ferrite materials can be very lossy at microwave frequencies, and rf interaction is reduced.

The ferrites are usually operated in the saturated state.

#### Curie temperature



The saturation magnetization of a material is a strong function of temperature, decreasing as temperature increases.

This effect can be understood by noting that the vibrational energy of an atom increases with temperature, making it more difficult to align all the magnetic dipoles.

At a high enough temperature a zero net magnetization results. This temperature is called the Curie temperature,  $T_c$ .

#### Properties of some ferrite materials

	Trans-Tech	$4\pi Ms$	$\Delta H$			$T_c$	$4\pi Mr$
Material	Number	G	Oe	$\epsilon_r$	$\tan \delta$	°C	G
Magnesium ferrite	TT1-105	1750	225	12.2	0.00025	225	1220
Magnesium ferrite	TT1-390	2150	540	12.7	0.00025	320	1288
Magnesium ferrite	TT1-3000	3000	190	12.9	0.0005	240	2000
Nickel ferrite	TT2-101	3000	350	12.8	0.0025	585	1853
Nickel ferrite	TT2-113	500	150	9.0	0.0008	120	140
Nickel ferrite	TT2-125	2100	460	12.6	0.001	560	1426
Lithium ferrite	TT73-1700	1700	<400	16.1	0.0025	460	1139
Lithium ferrite	TT73-2200	2200	<450	15.8	0.0025	520	1474
Yttrium garnet	G-113	1780	45	15.0	0.0002	280	1277
Aluminum garnet	G-610	680	40	14.5	0.0002	185	515

Why use  $4\pi M_s$ ? **B** =  $4\pi \mathbf{M} + \mathbf{H} = \mu \mathbf{H}$  (Gaussian unit)

The unit of  $\mathbf{B}$  is Gauss; the unit of  $\mathbf{H}$  is Oersted. They have same dimension.

#### What does $\Delta H$ and $M_r$ mean?

Ferrite linewidth and remanent magnetization

#### Anisotropic magnetic properties (I)

If  $\overline{H}$  is the applied ac field, the total magnetic field is  $\overline{H}_t = H_0 \hat{z} + \overline{H}$ ,

where  $|\overline{H}| \ll H_0$ . The field produced a total magnetization on the ferrite is given by  $\overline{M}_t = M_s \hat{z} + \overline{M}$ 

 $M_{\rm s}$  is the dc saturation magnetization and  $\overline{M}$  is the additional ac magnetization (in the *xy* plane) caused by applied field.

$$\frac{\overline{M}_{t} = M_{s}\hat{z} + \overline{M}}{\overline{H}_{t} = H_{0}\hat{z} + \overline{H}} } \Longrightarrow \frac{d\overline{M}}{dt} = -\mu_{0}\gamma\overline{M}\times H_{0}$$

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#### HIMAG & Trans-Tech特性比較

			Item		Unit	M C	easuring ondition	MZ-30	<u>MZ-2</u>	<u>MZ-4</u>	MZ-5	M 07
<sup>,</sup> 高科磁技 HIMAG		Initial Permeability		μi		100KHz 0.5mA	25	3000 ± 25%	2500 ± 25%	2400 ± 25%	5000 ± 25%	7000 ± 25%
		Core Loss		Рс г	nW/c.c.	25KHz sine way 200mT 100KHz sine way 200mT	25 60 100 120 25 7e 60 100 120	160 120 150 180	150 120 115 120 800 650 650 750	720 550 480 600		
		Relative L Factor	oss (	tan /µi *10-6)		10KHz 0.5mA 100KHz 0.5mA	25				4 35	6 45
		Saturation Density Remanenc Coercivity	Flux e	Bms Brms Hc	mT mT Oe	10KHz H= 1000A/1	25 M	430 150 0.15	450 150 0.15	430 150 0.15	400 130 0.12	400 130 0.1
• Tra	ns-Tec	furie temperata	re	Tc				>190	>210	>210	>130	>120
	Saturation Magnetization 4mM <sub>5</sub>	Landé g- Factor g- eff	Line Width õH oe @ - 3dB	Dielectric Constant E'	Dielectr Tangen	ic Loss t Tan=E*/E	Curie Temperature T <sub>e</sub> ( <sup>6</sup> C)	Spin Wave Line Width õH <sub>a</sub> oe	Remanent Induction B (Gauss)	Co Fo	ercive rce H <sub>c</sub> (oe)	Initial Permeability µ0
TTVG-800	800 ± 5%	2	<=15	13.9 ± 5%	< 0002		192	2.0	560	60	56	129
TTVG-930	930 ± 5%	2	c=10	14.0 ± 5%	<0002	0	188	2.0	380	40	%	225
TTVG-1000	1000 ± 5%	2	⇔10	14.0 ± 5%	< 0002	ž.	199	2.0	320	30	96	210
TTVG-1100	1100 ± 5%	2	<=10	14.1 ± 5%	<.0002	3	205	2.0	600	60	16	209

### Anisotropic magnetic properties (I)

The component equations of motion:

$$\frac{dM_x}{dt} = -\mu_0 \gamma M_y (H_0 + H_z) + \mu_0 \gamma (M_s + M_z) H_y$$
$$\frac{dM_y}{dt} = -\mu_0 \gamma M_x (H_0 + H_z) - \mu_0 \gamma (M_s + M_z) H_x$$
$$\frac{dM_z}{dt} = -\mu_0 \gamma M_x H_y + \mu_0 \gamma M_y H_x$$

#### Anisotropic magnetic properties (II)

Omitting higher order terms, the equations can be reduced to

 $\frac{dM_x}{dt} = -\omega_0 M_y + \omega_m H_y,$  $\frac{dM_y}{dt} = -(\omega_0 M_x + \omega_m H_x),$  $\frac{d^2 M_x}{dt^2} + \omega_0^2 M_x = \omega_m \frac{dH_y}{dt} + \omega_0 \omega_m H_x,$  $\frac{d^2 M_y}{dt^2} + \omega_0^2 M_y = -\omega_m \frac{dH_x}{dt} + \omega_0 \omega_m H_y.$  $\frac{dM_z}{dt} = 0$ , where  $\omega_0 = \mu_0 \gamma H_0$  and  $\omega_m = \mu_0 \gamma M_s$ If  $\overline{M}$  and  $\overline{H} \propto e^{j\omega t}$ , the above equations can be reduced to the phasor equations:  $(\omega_0^2 - \omega^2)M_x = \omega_0\omega_m H_x + j\omega\omega_m H_y,$   $(\omega_0^2 - \omega^2)M_y = -j\omega\omega_m H_x + \omega_0\omega_m H_y.$   $\overline{M} = \begin{bmatrix} \chi \end{bmatrix} \overline{H} = \begin{bmatrix} \chi_{xx} & \chi_{xy} & 0 \\ \chi_{yx} & \chi_{yy} & 0 \\ 0 & 0 & 0 \end{bmatrix} \overline{H},$ where  $\chi_{xx} = \chi_{yy} = \frac{\omega_0\omega_m}{\omega_0^2 - \omega^2}$  and  $\chi_{xy} = -\chi_{yx} = \frac{j\omega\omega_m}{\omega_0^2 - \omega^2}$ 

#### Anisotropic magnetic properties (III)

To relate *B* and *H*, we have  

$$\overline{B} = \mu_0(\overline{M} + \overline{H}) = [\mu]\overline{H} \implies [\mu] = \mu_0([U] + [\chi]) = \begin{bmatrix} \mu & j\kappa & 0 \\ -j\kappa & \mu & 0 \\ 0 & 0 & \mu_0 \end{bmatrix}$$

$$\begin{cases} \mu = \mu_0(1 + \chi_{xx}) = \mu_0(1 + \chi_{yy}) = \mu_0(1 + \frac{\omega_0\omega_m}{\omega_0^2 - \omega^2}) \\ \kappa = -j\mu_0\chi_{xy} = j\mu_0\chi_{yx} = \mu_0\frac{\omega\omega_m}{\omega_0^2 - \omega^2} \end{cases}$$

A material having a permeability tensor of this form is called gyrotropic.

How to apply this concept to a circularly polarized wave?

#### Forced precession of spinning electron (I)

If a small ac magnetic field is superimposed on the static field  $\mathbf{H}_{0}$ , the magnetic dipole moment will undergo a forced precession.

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Of particular interest is the case where the ac magnetic field is circularly polarized in the plane perpendicular to  $\mathbf{H}_{0}$ .

A right-hand circularly polarized wave can be expressed in phasor form as

$$\overline{H}^+ = H^+(\hat{x} - j\hat{y})$$

and in time-domain form as

$$\overline{H}^{+} = \operatorname{Re}\left\{\overline{H}^{+}e^{j\omega t}\right\} = H^{+}(\hat{x}\cos\omega t + \hat{y}\sin\omega t)$$

#### Forced precession of spinning electron (II)



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# Real and imaginary permeability & propagation and attenuation constant.



#### Faraday rotation --- a nonreciprocal effect



$$\overline{E}\Big|_{(z=\ell)} = \frac{E_0}{2}(\hat{x} - j\hat{y})e^{-j\beta_+\ell} + \frac{E_0}{2}(\hat{x} + j\hat{y})e^{-j\beta_-\ell}$$
$$= E_0 \bigg[\hat{x}\cos(\frac{\beta_+ - \beta_-}{2})\ell - \hat{y}\sin(\frac{\beta_+ - \beta_-}{2})\ell\bigg]e^{-j(\beta_+ + \beta_-)\ell/2}$$
$$\theta = \tan^{-1}\frac{E_y}{E_x} = -(\frac{\beta_+ - \beta_-}{2})\ell.$$
 This effect is called *Faraday rotation*.





Gyrator without a twist section.



Circular quide

Ferrite roo

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# Example : Circulator (I)

Circulator

Assembly



Fixture

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# **Circulator Measurement (II)**



## **Circulator Measured Results (III)**



## **Circulator Construction (IV)**



可否再簡化, i.e. cost down? Ans:需掌握關鍵技術→模擬分析能力。

## **Circulator Configuration (IV)**



# **Circulator Simulation (IV)**



全尺寸電磁場與熱分析模擬!





# Example #2: S 頻段微波循環器 (波導高功率)



優點: low insertion loss, high isolation, and low reflection p.s. 本實驗室陳乃慶、蔡育超、蔡鎮鴻設計。

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優點: low insertion loss, high isolation, and low reflection

$$\begin{split} \nabla \cdot \vec{E} &= 0 \\ \nabla \cdot (\hat{u} \cdot \vec{H}) &= 0 \\ \nabla \times \vec{E} &= i\omega \vec{B} = i\omega \hat{u} \cdot \vec{H} \\ \nabla \times \vec{E} &= i\omega \vec{B} = i\omega \hat{u} \cdot \vec{H} \\ \nabla \times \vec{H} &= \frac{\partial \vec{D}}{\partial t} = -i\omega \varepsilon \vec{E} \\ \hat{u} \cdot \vec{H} &= \begin{pmatrix} \mu & -i\kappa & 0 \\ i\kappa & \mu & 0 \\ 0 & 0 & \mu_0 \end{pmatrix} \begin{pmatrix} H_\rho \\ H_\phi \\ 0 \end{pmatrix} = \begin{pmatrix} \mu H_\rho - i\kappa H_\phi \\ i\kappa H_\rho + \mu H_\phi \\ 0 \end{pmatrix} \\ \vec{E} &= E_z(\rho, \phi) \hat{e}_z \\ \vec{H} &= H_\rho(\rho, \phi) \hat{e}_\rho + H_\phi(\rho, \phi) \hat{e}_\phi \end{split}$$

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$$\begin{split} \nabla \cdot \vec{E} &= \frac{\partial E_z}{\partial z} = 0 \\ \nabla \cdot (\hat{u} \cdot \vec{H}) &= \frac{1}{\rho} \frac{\partial}{\partial \rho} \Big[ \rho \Big( \mu H_\rho - i\kappa H_\phi \Big) \Big] + \frac{1}{\rho} \frac{\partial}{\partial \phi} \Big( i\kappa H_\rho + \mu H_\phi \Big) = 0 \\ \nabla \times \vec{E} &= i\omega \hat{u} \cdot \vec{H} \Rightarrow \hat{e}_\rho \frac{1}{\rho} \frac{\partial E_z}{\partial \phi} - \hat{e}_\phi \frac{\partial E_z}{\partial \rho} = i\omega \Big[ \hat{e}_\rho \Big( \mu H_\rho - i\kappa H_\phi \Big) + \hat{e}_\phi \Big( i\kappa H_\rho + \mu H_\phi \Big) \Big] \\ \nabla \times \vec{H} &= -i\omega \varepsilon \vec{E} \Rightarrow \frac{1}{\rho} \Bigg[ \frac{\partial \Big( \rho H_\phi \Big)}{\partial \rho} - \frac{\partial H_\rho}{\partial \phi} \Bigg] = -i\omega \varepsilon E_z \\ \begin{cases} H_\rho &= -\frac{1}{\omega \Big( \mu^2 - \kappa^2 \Big)} \Big( \frac{i\mu}{\rho} \frac{\partial E_z}{\partial \phi} + \kappa \frac{\partial E_z}{\partial \rho} \Big) \\ H_\phi &= \frac{1}{\omega \Big( \mu^2 - \kappa^2 \Big)} \Big( i\mu \frac{\partial E_z}{\partial \rho} - \frac{\kappa}{\rho} \frac{\partial E_z}{\partial \phi} \Big) \\ \Rightarrow \frac{\partial^2 E_z}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial^2 E_z}{\partial \rho} + \frac{1}{\rho^2} \frac{\partial^2 E_z}{\partial \phi^2} + \omega^2 \varepsilon \frac{\Big( \mu^2 - \kappa^2 \Big)}{\mu} E_z = 0 \\ \frac{1}{\rho} \Bigg[ \frac{\partial \Big( \rho H_\phi \Big)}{\partial \rho} - \frac{\partial H_\rho}{\partial \phi} \Bigg] = -i\omega \varepsilon E_z \end{split}$$

$$\begin{split} \frac{\partial^{2} E_{z}}{\partial \rho^{2}} + \frac{1}{\rho} \frac{\partial E_{z}}{\partial \rho} + \frac{1}{\rho^{2}} \frac{\partial^{2} E_{z}}{\partial \phi^{2}} + \omega^{2} \varepsilon \frac{\left(\mu^{2} - \kappa^{2}\right)}{\mu} E_{z} = 0 \\ \mu_{e} = \frac{\left(\mu^{2} - \kappa^{2}\right)}{\mu} , \quad \gamma^{2} = \omega^{2} \varepsilon \frac{\left(\mu^{2} - \kappa^{2}\right)}{\mu} = \omega^{2} \varepsilon \mu_{e} \\ \frac{\partial^{2} E_{z}}{\partial \rho^{2}} + \frac{1}{\rho} \frac{\partial E_{z}}{\partial \rho} + \frac{1}{\rho^{2}} \frac{\partial^{2} E_{z}}{\partial \phi^{2}} + \gamma^{2} E_{z} = 0 \\ E_{z} = \left(A_{m} e^{im\phi} + B_{m} e^{-im\phi}\right) J_{m}(\gamma_{mn}\rho) \\ H_{\rho} = -\frac{1}{\omega\left(\mu^{2} - \kappa^{2}\right)} \left( \left(\frac{i\mu}{\rho} \frac{\partial E_{z}}{\partial \phi} + \kappa \frac{\partial E_{z}}{\partial \rho}\right) \right) \\ = -\frac{\kappa \gamma_{mn}}{\omega\left(\mu^{2} - \kappa^{2}\right)} \left( \left(J'_{m}(\gamma_{mn}\rho) - \frac{m\mu}{\kappa \gamma_{mn}\rho} J_{m}(\gamma_{mn}\rho)\right) A_{m} e^{im\phi} + \left(J'_{m}(\gamma_{mn}\rho) + \frac{m\mu}{\kappa \gamma_{mn}\rho} J_{m}(\gamma_{mn}\rho)\right) B_{m} e^{-im\phi} \right) \\ H_{\phi} = \frac{1}{\omega\left(\mu^{2} - \kappa^{2}\right)} \left( \left(J'_{m}(\gamma_{mn}\rho) - \frac{m\kappa}{\mu \gamma_{mn}\rho} J_{m}(\gamma_{mn}\rho)\right) A_{m} e^{im\phi} + \left(J'_{m}(\gamma_{mn}\rho) + \frac{m\kappa}{\mu \gamma_{mn}\rho} J_{m}(\gamma_{mn}\rho)\right) B_{m} e^{-im\phi} \right) \\ = -\frac{i\mu \gamma_{mn}}{\omega\left(\mu^{2} - \kappa^{2}\right)} \left( \left(J'_{m}(\gamma_{mn}\rho) - \frac{m\kappa}{\mu \gamma_{mn}\rho} J_{m}(\gamma_{mn}\rho)\right) A_{m} e^{im\phi} + \left(J'_{m}(\gamma_{mn}\rho) + \frac{m\kappa}{\mu \gamma_{mn}\rho} J_{m}(\gamma_{mn}\rho)\right) B_{m} e^{-im\phi} \right) \\ \end{array}$$

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$$\begin{split} E_{z} &= (A_{1}e^{i\phi} + B_{1}e^{-i\phi})J_{1}(\gamma\rho) \\ E_{z}(\rho = R, \phi) &= \begin{cases} E_{0} , \phi = 0 \\ -E_{0} , \phi = \frac{2\pi}{3} \\ 0 , \phi = \frac{4\pi}{3} \end{cases} \\ \Rightarrow A_{1} &= \frac{E_{0}}{2J_{1}(\gamma R)} \left(1 + i\frac{1}{\sqrt{3}}\right) & \& B_{1} = \frac{E_{0}}{2J_{1}(\gamma R)} \left(1 - i\frac{1}{\sqrt{3}}\right) \\ E_{z} &= (A_{1}e^{i\phi} + B_{1}e^{-i\phi})J_{1}(\gamma\rho) = \left(\frac{E_{0}}{2J_{1}(\gamma R)} \left(1 + i\frac{1}{\sqrt{3}}\right)e^{i\phi} + \frac{E_{0}}{2J_{1}(\gamma R)} \left(1 - i\frac{1}{\sqrt{3}}\right)e^{-i\phi}\right)J_{1}(\gamma\rho) \\ &= \frac{E_{0}}{J_{1}(\gamma R)}J_{1}(\gamma\rho) \left(\cos\phi - \frac{\sin\phi}{\sqrt{3}}\right) \end{split}$$

$$\begin{split} \overline{B.C. \Rightarrow \hat{n} \times \vec{H}}\Big|_{\rho=R} &= 0 \Rightarrow -\hat{e}_{\rho} \times \vec{H}\Big|_{\rho=R} = 0 \Rightarrow H_{\phi}\Big|_{\rho=R} = 0 \\ H_{\phi}\Big|_{\rho=R} &= \frac{i\mu\gamma_{mn}}{\omega(\mu^{2} - \kappa^{2})} \Biggl( \Biggl(J'_{m}(\gamma_{mn}R) - \frac{m\kappa}{\mu\gamma_{mn}}J_{m}(\gamma_{mn}R)\Biggr) A_{m}e^{im\phi} - \Biggl(J'_{m}(\gamma_{mn}R) + \frac{m\kappa}{\mu\gamma_{mn}}J_{m}(\gamma_{mn}R)\Biggr) B_{m}e^{-im\phi}\Biggr) = 0 \\ H_{\phi}\Big(\rho = R, \phi\Big) &= \begin{cases} H_{0} & \text{for } -\psi < \phi < \psi \\ H_{0} & \text{for } 120^{\circ} + \psi < \phi < 120^{\circ} + \psi \\ 0 & \text{elsewhere} \end{cases} \\ H_{\phi}\Big(\rho = R, \phi\Big) &= \sum_{m=-\infty}^{\infty} C_{m}e^{im\phi} = \frac{2H_{0}\psi}{\pi} + \frac{H_{0}}{\pi}\sum_{m=1}^{\infty}\frac{\sin(m\psi)}{m} \Biggl( \Biggl(1 + e^{-i\frac{2m\pi}{3}}\Biggr) e^{im\phi} + \Biggl(1 + e^{i\frac{2m\pi}{3}}\Biggr) e^{-im\phi} \Biggr) \\ m = 1 \Rightarrow H_{\phi}\Big(\rho = R, \phi\Big) &= \frac{H_{0}\sin\psi}{2\pi} \Bigl( (1 - i\sqrt{3})e^{i\phi} + (1 + i\sqrt{3})e^{-i\phi} \Bigr) \\ &= -\frac{\gamma E_{0}}{2\sqrt{3}\omega\mu_{e}J_{1}(\gamma R)} \Biggl( \Biggl(J'_{1}(\gamma R) - \frac{\kappa}{\mu\gamma R}J_{1}(\gamma R)\Biggr) \Bigl(1 - i\sqrt{3} e^{i\phi} + \Biggl(J'_{1}(\gamma R) + \frac{\kappa}{\mu\gamma R}J_{1}(\gamma R)\Biggr) \Bigl(1 + i\sqrt{3} e^{-i\phi} \Biggr) \\ &= \frac{H_{0}\sin\psi}{2\pi} = -\frac{\gamma E_{0}}{2\sqrt{3}\omega\mu_{e}J_{1}(\gamma R)} \Biggl( J'_{1}(\gamma R) - \frac{\kappa}{\mu\gamma R}J_{1}(\gamma R) \Biggr) \\ &= \frac{H_{0}\sin\psi}{2\pi} = \frac{\gamma E_{0}}{2\sqrt{3}\omega\mu_{e}J_{1}(\gamma R)} \Biggl( J'_{1}(\gamma R) + \frac{\kappa}{\mu\gamma R}J_{1}(\gamma R) \Biggr) \\ &= \frac{H_{0}\sin\psi}{2\pi} = \frac{\gamma E_{0}}{2\sqrt{3}\omega\mu_{e}J_{1}(\gamma R)} \Biggl( J'_{1}(\gamma R) + \frac{\kappa}{\mu\gamma R}J_{1}(\gamma R) \Biggr) \\ &= \frac{H_{0}\sin\psi}{2\pi} = \frac{\gamma E_{0}}{2\sqrt{3}\omega\mu_{e}J_{1}(\gamma R)} \Biggl( J'_{1}(\gamma R) + \frac{\kappa}{\mu\gamma R}J_{1}(\gamma R) \Biggr) \\ &= \frac{H_{0}\sin\psi}{2\pi} = \frac{E_{0}}{\sqrt{3}\omega\mu_{e}J_{1}(\gamma R)} \Biggr( J'_{1}(\gamma R) + \frac{\kappa}{\mu\gamma R}J_{1}(\gamma R) \Biggr) \\ &= \frac{H_{0}\sin\psi}{2\pi} = \frac{E_{0}}{\sqrt{3}\omega\mu_{e}J_{1}(\gamma R)} \Biggr) \\ &= \frac{\pi}{2\sqrt{3}\omega\mu_{e}J_{1}(\gamma R)} \Biggr( J'_{1}(\gamma R) + \frac{\kappa}{\mu\gamma R}J_{1}(\gamma R) \Biggr) \\ &= \frac{H_{0}\sin\psi}{2\pi} = \frac{\pi}{2\sqrt{3}\omega\mu_{e}J_{1}(\gamma R)} \Biggr( J'_{1}(\gamma R) + \frac{\kappa}{\mu\gamma R}J_{1}(\gamma R) \Biggr)$$

$$\begin{split} H_{\rho} &= -\frac{\kappa\gamma_{\rm mn}}{\omega(\mu^2 - \kappa^2)} \Biggl[ \Biggl( \mathbf{J}'_{\rm m}(\gamma_{\rm mn}\rho) - \frac{m\mu}{\kappa\gamma_{\rm mn}\rho} \mathbf{J}_{\rm m}(\gamma_{\rm mn}\rho) \Biggr] \mathbf{A}_{\rm m} \mathrm{e}^{\mathrm{i}\mathrm{m}\phi} + \Biggl( \mathbf{J}'_{\rm m}(\gamma_{\rm mn}\rho) + \frac{m\mu}{\kappa\gamma_{\rm mn}\rho} \mathbf{J}_{\rm m}(\gamma_{\rm mn}\rho) \Biggr] \mathbf{B}_{\rm m} \mathrm{e}^{\mathrm{i}\mathrm{m}\phi} \Biggr] \\ \mathbf{A}_{1} &= \frac{E_{0}}{2\mathbf{J}_{1}(\gamma R)} \Biggl( \mathbf{1} + i\frac{1}{\sqrt{3}} \Biggr) \quad \& \quad \mathbf{B}_{1} = \frac{E_{0}}{2\mathbf{J}_{1}(\gamma R)} \Biggl( \mathbf{1} - i\frac{1}{\sqrt{3}} \Biggr) \end{split}$$

m = 1, n = 1

$$\begin{split} H_{\rho} &= -\frac{\kappa\gamma_{11}}{\omega(\mu^{2} - \kappa^{2})} \Biggl( \Biggl( J_{1}'(\gamma_{11}\rho) - \frac{\mu}{\kappa\gamma_{11}\rho} J_{1}(\gamma_{11}\rho) \Biggr) A_{1} e^{i\phi} + \Biggl( J_{1}'(\gamma_{11}\rho) + \frac{\mu}{\kappa\gamma_{11}\rho} J_{1}(\gamma_{11}\rho) \Biggr) B_{1} e^{-i\phi} \Biggr) \\ &= -\frac{\kappa\gamma_{11}E_{0}}{2\omega(\mu^{2} - \kappa^{2}) J_{1}(\gamma_{11}R)} \Biggl( \Biggl( J_{1}'(\gamma_{11}\rho) - \frac{\mu}{\kappa\gamma_{11}\rho} J_{1}(\gamma_{11}\rho) \Biggr) \Biggl( 1 + i\frac{1}{\sqrt{3}} \Biggr) e^{i\phi} + \Biggl( J_{1}'(\gamma_{11}\rho) + \frac{\mu}{\kappa\gamma_{11}\rho} J_{1}(\gamma_{11}\rho) \Biggr) \Biggl( 1 - i\frac{1}{\sqrt{3}} \Biggr) e^{-i\phi} \Biggr) \\ &= -\frac{\kappa\gamma_{11}E_{0}}{\omega(\mu^{2} - \kappa^{2}) J_{1}(\gamma_{11}R)} \Biggl( \Biggl( J_{1}'(\gamma_{11}\rho) - i\frac{\mu}{\kappa\gamma_{11}\rho} \frac{J_{1}(\gamma_{11}\rho)}{\sqrt{3}} \Biggr) \cos\phi - \Biggl( \frac{J_{1}'(\gamma_{11}\rho)}{\sqrt{3}} + \frac{i\mu}{\kappa\gamma_{11}\rho} J_{1}(\gamma_{11}\rho) \Biggr) \sin\phi \Biggr) \\ H_{\rho}(\rho = R, \phi) &= -\frac{\kappa\gamma_{mn}}{\omega(\mu^{2} - \kappa^{2})} \Biggl( \Biggl( -J_{m}(\gamma_{mn}R) A_{m} e^{im\phi} + \Biggl( \frac{m\mu}{\kappa\gamma_{mn}R} J_{m}(\gamma_{mn}R) \Biggr) B_{m} e^{-im\phi} \Biggr) \\ &= \frac{m\mu}{\omega R(\mu^{2} - \kappa^{2})} \Biggl( A_{m} e^{im\phi} - B_{m} e^{-im\phi} \Biggr) J_{m}(\gamma_{mn}R) = \frac{\mu}{\omega R(\mu^{2} - \kappa^{2})} \Biggl( A_{1} e^{i\phi} - B_{1} e^{-i\phi} \Biggr) J_{1}(\chi_{11}) \\ &= \frac{\mu E_{0}}{2\omega R(\mu^{2} - \kappa^{2})} \Biggl( \Biggl( 1 + i\frac{1}{\sqrt{3}} \Biggr) e^{i\phi} - \Biggl( 1 - i\frac{1}{\sqrt{3}} \Biggr) e^{-i\phi} \Biggr) = \frac{iH_{0}}{\kappa'_{11}} \Biggl( \sin\phi + \frac{1}{\sqrt{3}} \cos\phi \Biggr) \end{split}$$

$$E_{z} = \frac{E_{0}}{J_{1}(\gamma R)} J_{1}(\gamma \rho) \left(\cos \phi - \frac{\sin \phi}{\sqrt{3}}\right) = \frac{E_{0}}{J_{1}(x_{11}')} J_{1}(\frac{x_{11}'\rho}{R}) \left(\cos \phi - \frac{\sin \phi}{\sqrt{3}}\right)$$

$$\begin{cases} J_{1}'(\gamma R) = 0 \quad \Rightarrow \boxed{\gamma_{11}R = x_{11}' = 1.841 = \omega_{110}\sqrt{\varepsilon\mu_{e}}R} \\ H_{0} \sin \psi = \frac{E_{0}}{\sqrt{3}\omega\mu_{e}} \frac{\kappa}{\mu R} \Rightarrow \frac{E_{0}}{H_{0}} = \frac{\sqrt{3}\omega_{110}\mu_{e}\mu R \sin \psi}{\pi \kappa} = \frac{\sqrt{3}\mu_{e}\mu \sin \psi}{\pi \kappa} \frac{1.841}{\sqrt{\varepsilon\mu_{e}}} \\ \frac{E_{0}}{H_{0}} = \frac{\sqrt{3}\omega_{110}\mu_{e}\mu R \sin \psi}{\pi \kappa} = \sqrt{\frac{3\mu_{e}}{\varepsilon}} \frac{1.841\mu \sin \psi}{\pi \kappa} = \sqrt{\frac{\mu_{e}}{\varepsilon}} \Rightarrow \boxed{\sin \psi = \frac{\pi}{1.841\sqrt{3}} \left(\frac{\kappa}{\mu}\right)} \\ \sin \psi = \frac{\pi}{1.841\sqrt{3}} \left(\frac{\kappa}{\mu}\right) = \frac{\pi}{1.841\sqrt{3}} \left(\frac{\omega\omega_{m}}{\omega_{0}^{2} - \omega^{2} + \omega_{0}\omega_{m}}\right)} \end{cases}$$

$$H_{\phi}(\rho,\phi) = -\frac{\gamma E_{0}}{2\sqrt{3}\omega\mu_{c}}J_{1}(x_{11}') \left( \left(J_{1}'(\gamma\rho) - \frac{\kappa}{\mu\gamma\rho}J_{1}(\gamma\rho)\right) \left(1 - i\sqrt{3}\right)e^{i\phi} + \left(J_{1}'(\gamma\rho) + \frac{\kappa}{\mu\gamma\rho}J_{1}(\gamma\rho)\right) \left(1 + i\sqrt{3}\right)e^{-i\phi} \right)$$

$$x = \gamma\rho \Rightarrow \begin{cases} J_{1}'(x) - \frac{\kappa}{\mu x}J_{1}(x) = 0 \\ J_{1}'(x) + \frac{\kappa}{\mu x}J_{1}(x) = 0 \end{cases} \Rightarrow \begin{cases} J_{1}'(x^{-}) - \frac{\kappa}{\mu x^{-}}J_{1}(x^{-}) = 0 \\ J_{1}'(x) + \frac{\kappa}{\mu x}J_{1}(x) = 0 \end{cases}$$





#### **HSS Simulation**



#### Example 1 :







\* ¥

45





#### **Example 2 :**



48



910

920

930

940

f(MHz)

950

960

970



View/Edit Material for

Active Design

.... Definitions

Material Name YG-357

Properties of the Material

Name

Type Value

Units

51

980